



SOME METHODS FOR GENERATION & GRID OPTIMIZATION UNDER LONG-RUN UNCERTAINTIES

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Policy, and Technology Shifts
Session on “Modernizing Planning through Technology and Data: Smarter, Faster, and Leaner
Planning Enabled by AI, Automation, and Computational Advances.”***

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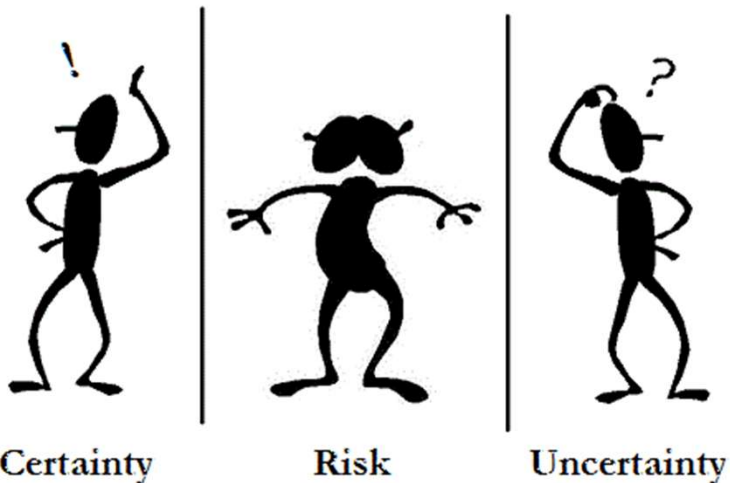
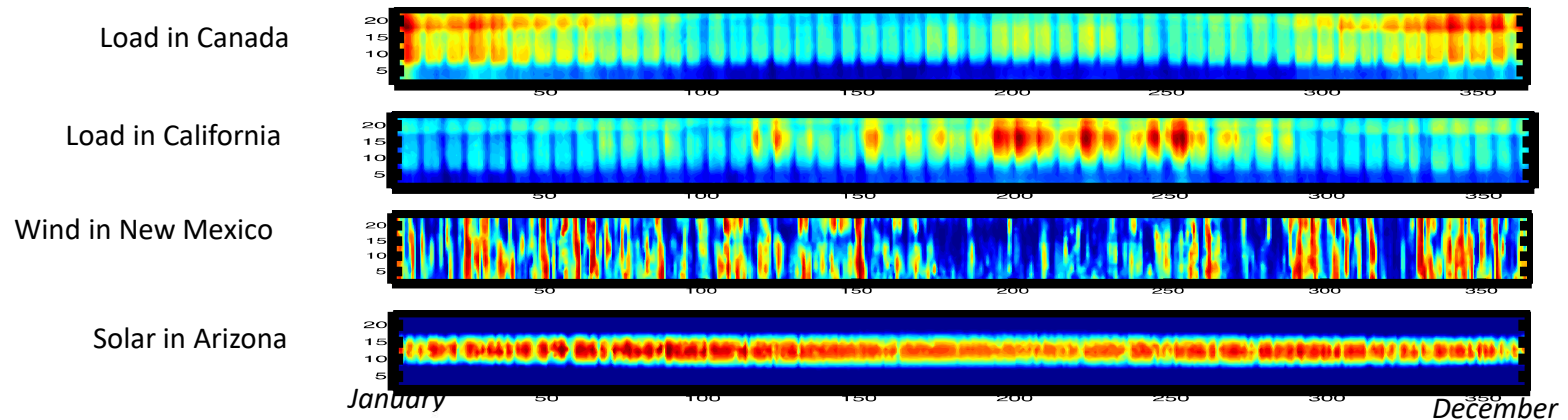
Overview

- I. Uncertainty-aware planning: Why?
- II. Stochastic Programming
- III. Robust Programming
- IV. Results for BPA & WECC-wide analyses
 - Q1:** Do stochastic grid plans *differ*?
 - Q2:** Are stochastic plans *better*?
 - Q3:** Which uncertainty *matters* most?
 - Q4:** What is *benefit of SP* compared to other model enhancements?
(*more hours, DC load flow, unit commitment*)
- V. Decomposition & AI to enhance computability

I. Why Uncertainty-Aware Planning?

Two challenges:

1. Operating Variability (over hours):



2. Hyper-uncertainty (over decades):

- Fuel Costs
- Demand Growth
- Technology Costs
- Carbon Policy
- DR
- PEV
- RPS
- Distributed Generation
- Coal Retirements

What Can We Learn from Uncertainty-Aware Planning?

1. Do risks of some projects justify “wait & see”?

- Given stranded asset risks, defer until need clearer?
- “Option value” of delay should be quantified

→ ***Might build less under uncertainty***

2. Do some projects have a “flexibility” or “insurance” value that justifies their upfront costs?

- Does a project open up more options to deal with multiple possible futures?
- Does a project enhance exchanges between regions that hedge risks?
- Does a project provide insurance against extreme scenarios?

→ ***Might build more under uncertainty***

How to assess uncertainty-aware planning frameworks?

(Spyrou, Hobbs et al. 2024)

How much \$ can we save by explicitly considering risks?

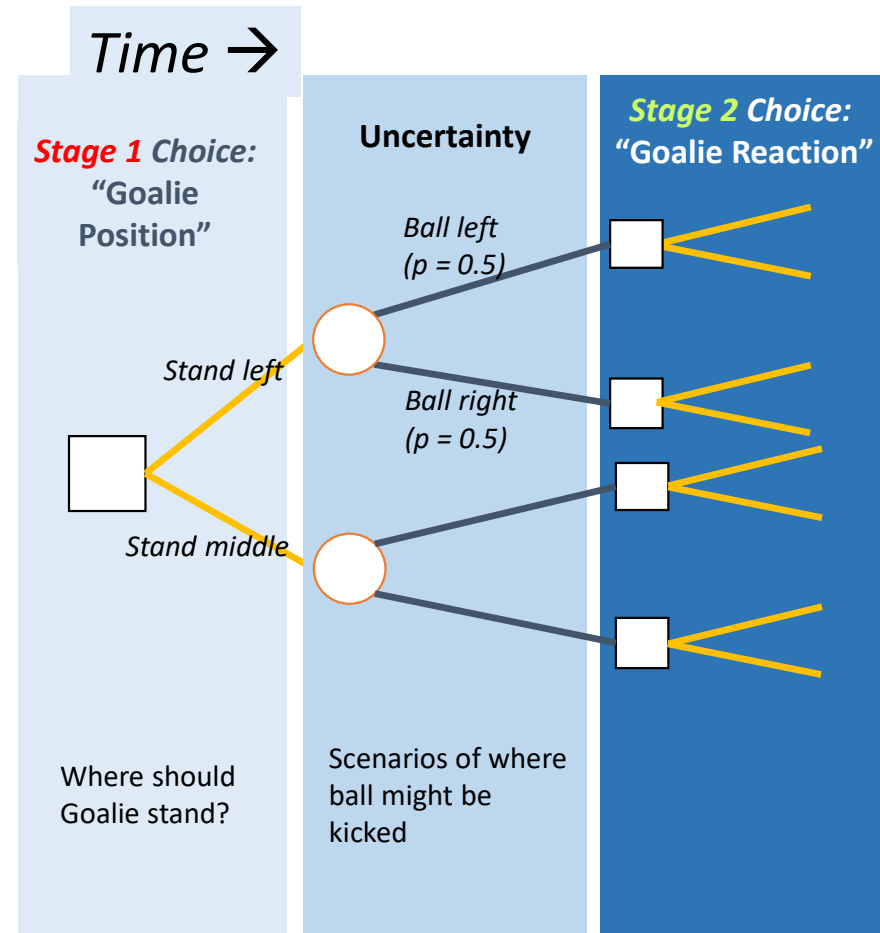
| | <i>Criterion 1: Methodological capability</i> | | | <i>Criterion 3: Contribution to decision making and stakeholder acceptance</i> | |
|---|---|---|---|---|--|
| Theme | How the methodological framework considers: | | | Engagement goal | Number of views |
| Uncertainty | Space of possible states | Probabilities of states | Chronological evolution | For each theme in the 1 st column, which goal could the framework serve: to inform, to consult, or to collaborate? | For each theme in the 1 st column, can the framework consider multiple views and how? |
| Plans | Feasible set | Asset-temporal-spatial resolution | Future updates to plans | | |
| Consequences: Attributes | Types (e.g., reliability, cost) | Resolution | Precision | | |
| Consequences: Assessment | Different types of criteria (e.g., min-max) | Updates to criteria for assessment of plans | Process to elicit preferences | | |
| | | | | | |
| <i>Criterion 2: Practical applicability</i> <ul style="list-style-type: none">Computational resources<ul style="list-style-type: none">Software | | | <ul style="list-style-type: none">Data requirementsHuman resourcesRegulatory compliance | | |

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II. How does Stochastic Programming (SP) work? Uncertainty & Adaptation as a “Decision Tree”

- The optimum for **Stage 1** considers:
 - Each scenario's probability
 - How you'd adapt in **Stage 2**, given:
 - ✓ the scenario
 - ✓ options left open by **Stage 1** decisions
- **Stage 1**'s optimum might not be best for any individual scenario
 - ➔ Must evaluate flexibility provided by **Stage 1** choice under all scenarios at once



“Decision Tree” Calculations: Logic of Stochastic Optimization

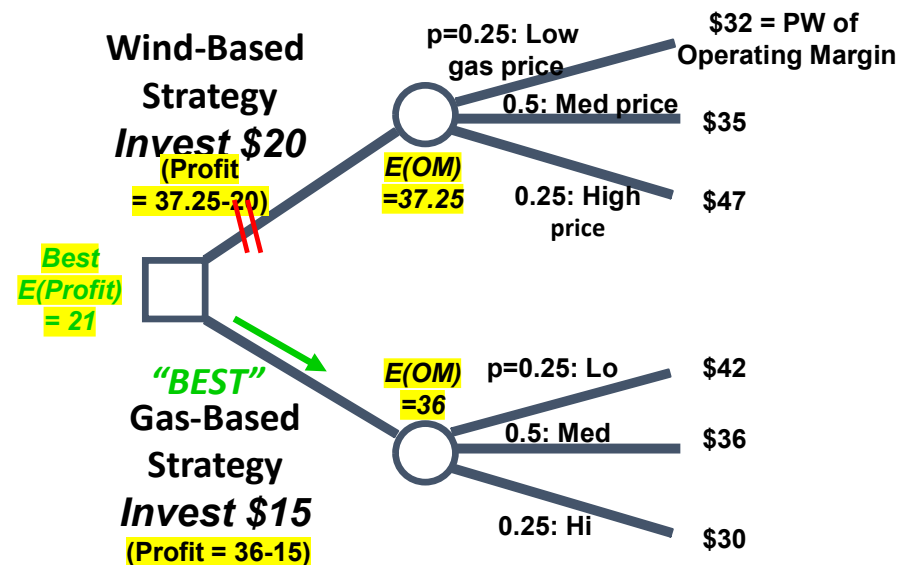
Simple example: Choose Resource

(1) Start at right end

(2) Move left

- at a chance node, calculate “expected value”
- at a decision node, choose best alternative

(3) Continue until reach left-most node

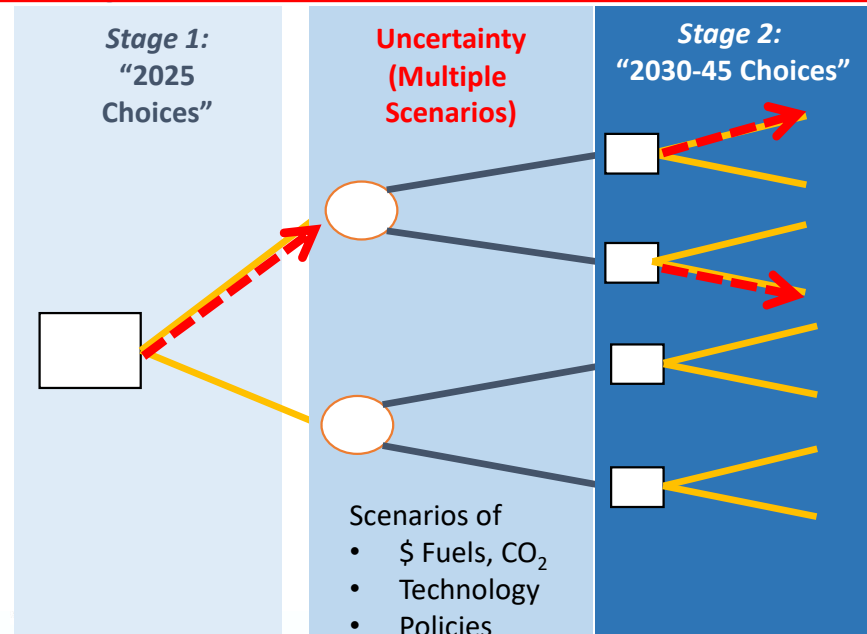
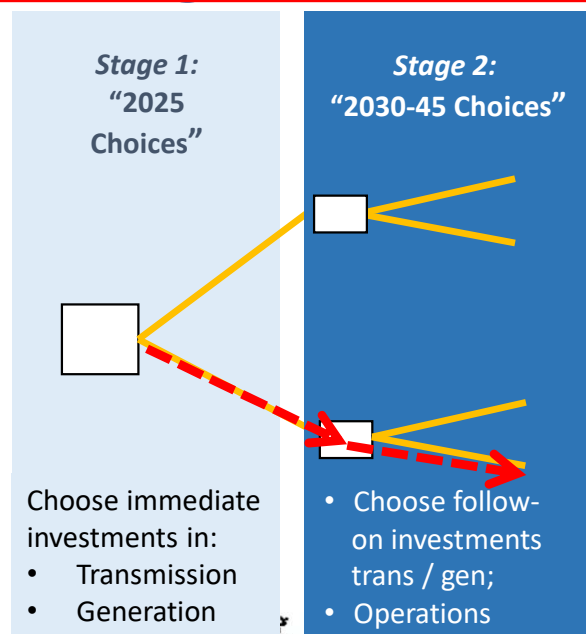


Decision
Node:
2025
decision

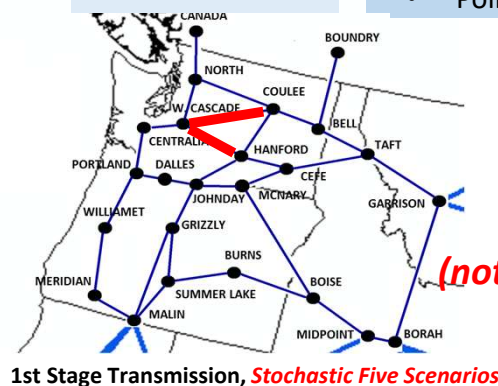
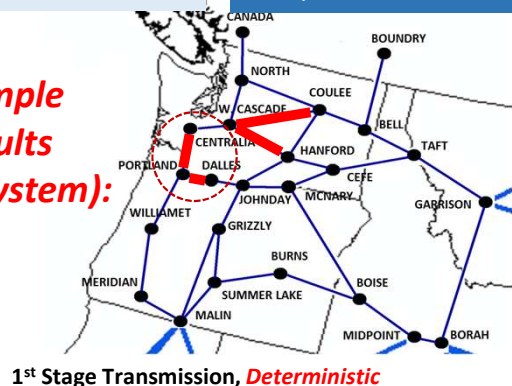
Chance nodes:
Gas Prices
2025-2045

Optimal operations:
Operating Margin
(Revenue – O&M)

Multistage (Adaptive) Grid Planning: Single Scenario (Deterministic) vs. Multiscenario



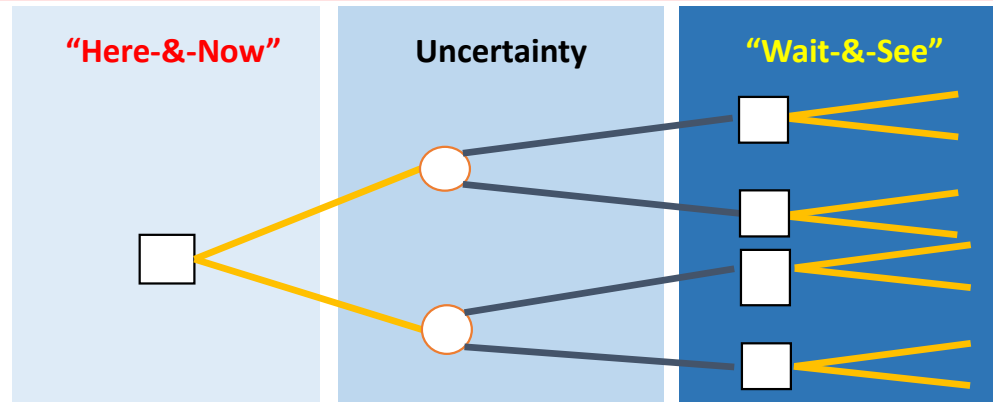
**Example Results
(BPA System):**



Stage 1 Decisions:
"PUT OFF CHOICE"
(not "INVEST MORE: INSURE & DIVERSIFY")

SP's Math Formulation: MILP

(van der Weijde, Hobbs, *Energy Economics*, 2012; Munoz, Hobbs et al., *IEEE TPWRS*; Xu, Hobbs in *Transmission Investment in Liberalized Markets*, 2020)



$$\text{MIN NPV Cost} = C_1 X_I + \sum_{\text{scenarios } S} (P_S * C_2 X_{2,S})$$

$$\text{Subject to: } A_{1,1} X_I \leq B_1$$

$$\{A_{2,1,S} X_I + A_{2,2,S} X_{2,S} \leq B_{2,S}\}, \quad \forall S$$

- **Decision variables X 's include:**

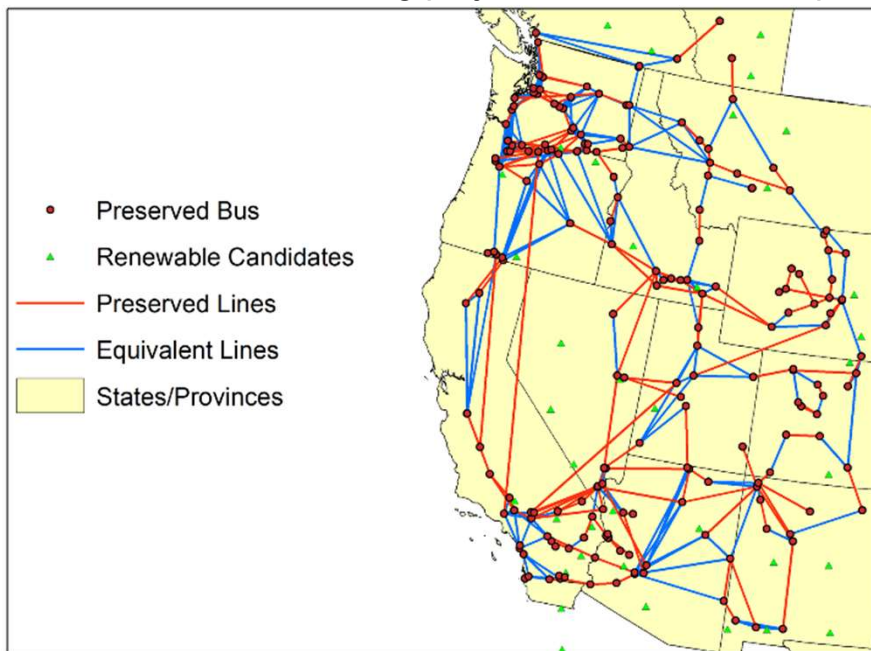
- **Investments:** transmission (and if "cooptimize": gen, DSM, storage)
- **Operations:** generator, storage, DR dispatch, phase shifter settings...
(production costing or short-run market simulation)

- **Constraints include:**

- Kirchhoff's Laws
- Generator and transmission capacity / operating restrictions
- Siting restrictions
- Emissions caps, renewable portfolio standards

Our Hypothetical BPA Implementation of JHSMINE (Johns Hopkins Stochastic Multistage Integrated Network Evaluation)

- BPA/WECC Stochastic Programming model (JHU):
 - Here-&-now: Decide 2018, online 2024
 - Wait-&-see: Decide 2024, online 2030
 - 8 Scenarios, 11 Uncertain variables
- $\sim 10^1$ load blocks per year (so could solve many times)
- Investment variables:
 - All WECC lines
 - New unannounced siting projections: assume competitive generators respond to LMPs



Example 300-bus network

(developed by JHU for WECC analyses, with help of ASU)

Pipes & Bubbles or Linearized DC OPF (KCL/KVL)

Uncertainties considered in hypothetical BPA/WECC study

| | Uncertainty | Hi (3) | Lo (1) | Medium |
|----|--|------------------------------------|---------------------------------|--|
| 1 | Carbon Cost Years Implement | 2020 | Never | 2026 |
| 2 | Wind Build cost decay rate | 6 times base case decay rate | 0.75 times base case decay rate | Defined by NREL ATB Rate varies by Year |
| 3 | Solar Build cost decay rate | 2 times base case decay rate | 0.75 times base case decay rate | Defined by NREL ATB Rate varies by Year |
| 4 | Fuel Price | 2% APR | 0.25% APR | 1.125% (average of 2% and 0.25%) |
| 5 | Base Demand Growth (Each area demand growth determined by base + Area specific demand growth) | 1.92% (1.5 times base value) | 0.565% (Half base value) | 1.13% |
| 6 | Base Peak Demand (Each area peak growth determined by base + Area specific demand growth) | 1.7% APR (1.5 times base value) | 0.64% APR (Half base value) | 1.28% APR |
| 7 | Hydro CF | 1.35 x base values | 0.65 x base values | 1 x base values |
| 8 | Initial Line Multiplier | 1.25 x base costs | 1.25 x base costs | 1.25 x base costs |
| | Late Line Multiplier | 1.5 x base costs | 1 x base costs | 1.25 x base costs |
| 9 | Total Solar subgrid Init Penetration | 0.10% | 0.10% | 0.10% |
| | Total Solar subgrid linear AGR | 0.60% | 0.20% | 0.4% (average of 0.6% and 0.2%) |
| 10 | DER Solar subgrid Init Penetration | 0.10% | 0.10% | 0.10% |
| | DER Solar subgrid linear AGR | 0.22% | 0.05% | 0.0135% (average of 0.22% and 0.05%) |
| 11 | Solar SW Init Penetration | 2.00% | 2.00% | 2.00% |
| | Solar SW linear AGR | 0.80% | 0.50% | 0.65% (average of 0.8% and 0.5%) |

| Scenario # | Probability | Scenario String |
|------------|-------------|-----------------|
| 1 | 0.125 | 33331113333 |
| 2 | 0.125 | 33131113111 |
| 3 | 0.125 | 31313333333 |
| 4 | 0.125 | 31111131111 |
| 5 | 0.125 | 13333313333 |
| 6 | 0.125 | 13133313111 |
| 7 | 0.125 | 11311131333 |
| 8 | 0.125 | 11113333111 |

Summary: Introduction to SP

- SP asks: what choices *now* minimize prob-weighted cost, considering:
 - Impacts over all scenarios
 - *Immediate* “here-&-now” decisions:
 - Made without knowing which scenario will occur
 - Hem in or open up later options
 - *Later* “wait-&-see”/recourse decisions:
 - Adaptation made *after* knowing which scenario will occur
- SP widely used in power systems (see references) and other fields
 - 100M variables or more handled in gen-trans planning problems using decomposition methods (Munoz, Watson, Hobbs, 2016)
- Elaborate versions can consider ≥ 2 decision stages
- But: *Curse* of dimensionality: # variables go up exponentially

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III. Another Approach: Robustness-Based Methods

➤ ~~Scenarios + Probabilities~~ → Uncertainty Set

- ✓ Either a Set of Scenarios or Continuous Range of Possible Futures
- ✓ Maximize Robustness: Minimize {worst outcome among all scenarios/possible outcomes}
- ✓ Three well-known “Robustness” methods:

(1) **“Robust Optimization”**: Choose plan to MIN worst outcome over infinite set of possible futures (Malcolm, Zenios 1994)

- ✓ Highly challenging for large problems, especially if later “adaptation” (wait-and-see recourse)

(2) **“Robust Decision Making”**: (a) Define set of candidate plans,
(b) evaluate each under each scenario,
(c) choose plan to MIN worst outcome over scenarios (Cervigni et al. 2015)

- ✓ Computationally practical, but no recourse/adaptation

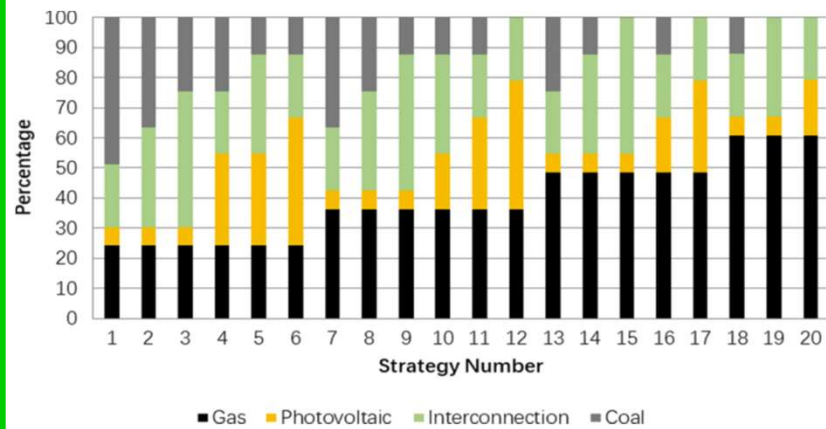
(3) **“Adaptive Robust DM”**: (a) Define set of candidate *base* plans,
(b) under each scenario, *“adapt”* plan under scenarios where it does badly,
(c) choose plan to MIN worst *“adapted”* outcome over scenarios (Moreira et al. 2016)

- ✓ There are many methods to identify plan/scenario combinations that need adaptation (Step (b)); then use heuristics or optimization for Step (c)

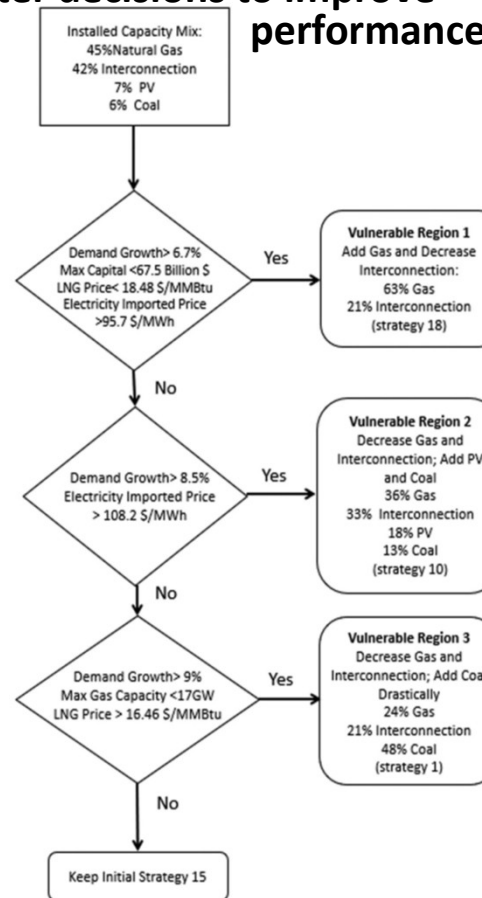
Adaptive RDM for Bangladesh Power Sector (World Bank)

(Jiang, Vogt-Schilb, Spyrou, Hobbs, 2025)

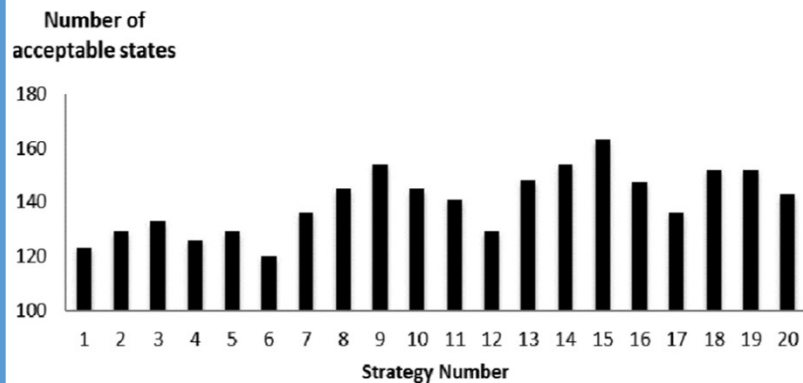
Step (a) Define set of plans to evaluate



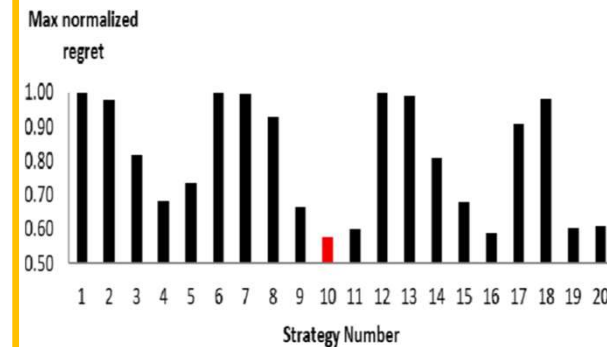
Step (b) (Cont'd) ... & then adapt later decisions to improve performance



Step (b) ID unacceptable plan-scenario combos



Step (c) Choose plan that MIN worst performance



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IV. SP vs. Single-Scenario (“Deterministic”) Model

- Deterministic provides best plan for 1 scenario
 - gives insight into other scenarios only through laborious sensitivity analysis
- SP balances first cost vs. robustness to various scenarios
- The “cost” to use SP is:
 - Time/effort to characterize uncertainties
 - ➔ Need to automate this process
 - Computational intensity
 - ➔ Deploy decomposition with HPC

What Difference Does SP Make Relative to Single Scenario Optimization?

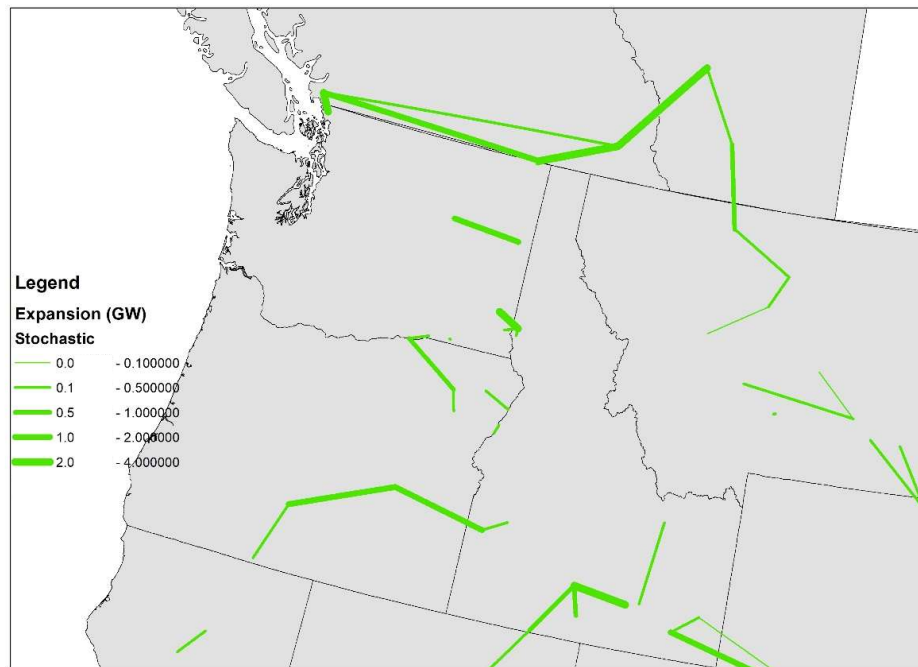
- Impact: *If you consider all scenarios at once, what happens to:*
 1. “Here-&-now” grid investments?
 2. Probability-weighted cost? (saved \$ from optimizing 1st stage investment?)
 - Effective risk-hedges
 - Avoid stranded assets

- How to quantify the benefit of including uncertainty?
 - Step 1, Consider all 8 scenarios:
 - Full SP → build **X** in first stage (2018), expected cost = **\$670B**
 - Step 2, Consider only 1 scenario (“medium” values for 11 uncertain variables)
 - Single scenario model → build **Y** in 1st stage. Do immediate investments change?
 - Then re-run full SP, but constrain 2018 decisions = **Y**
 - But all other decisions unconstrained (post-2018 lines, generator investment)
 - Cost increases (adding constraints increases cost) to say **\$672B**
 - “**Benefit of including uncertainty**” = increase in cost (**\$2B**). Does the change matter?

Q1: How do SP vs. deterministic grid plans differ: 1st Stage Grid Investments

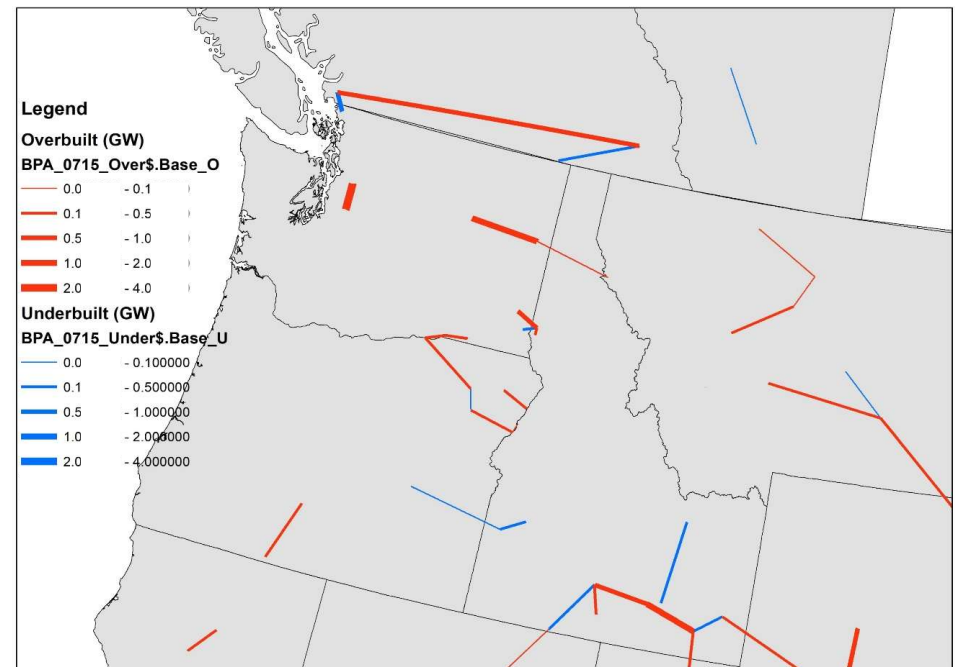
1st Stage Solution (decide in 2018, online in 2024 in all scenarios)

→ *Uncertainty-aware optimization delays some investments (“wait for information”); but expands others (as “insurance”)*



Stochastic Programming

1st stage transmission expansion Cost:
WECC-wide: \$5240M; BPA: \$706M



Single Scenario Solution (All “Medium”): Changes relative to SP (Blue is underbuilt; Red is overbuilt compared to SP solution)

1st stage transmission investment:
WECC-wide: \$5310M, BPA \$934M

Q2: Benefit of Including Multiple Long Run Scenarios

- Benefit of including uncertainty for planning 1st stage **BPA** internal & intertie lines: **\$320M** (Expected present worth EPW)
- ... And for planning 1st stage **WECC** internal & intertie lines : **\$1675M** (EPW)

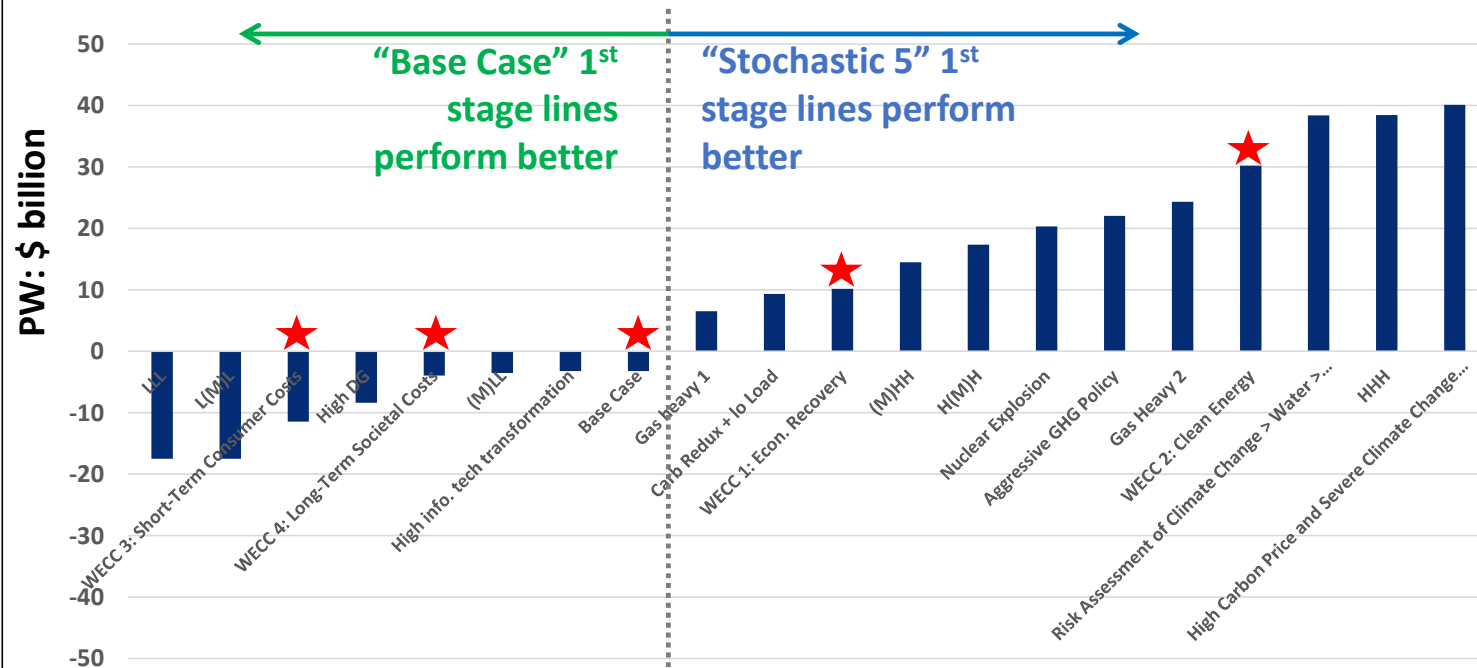
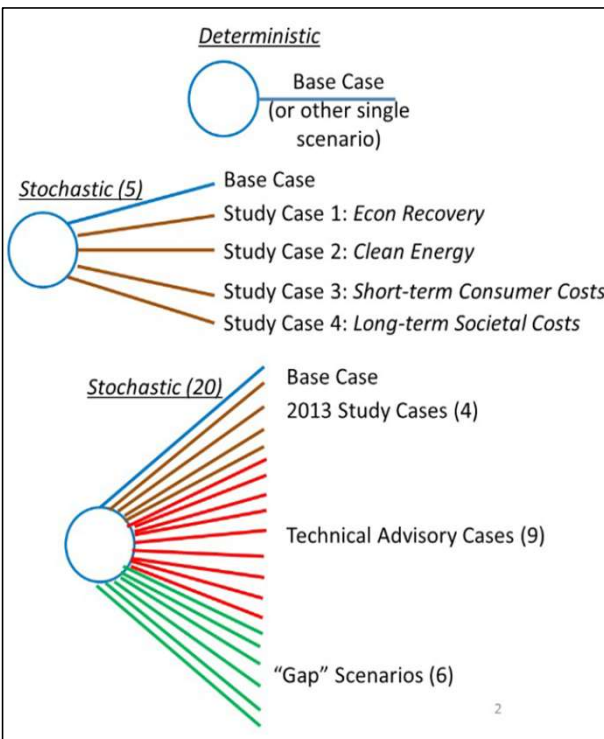
Q2: Are stochastic solutions better for unconsidered scenarios?

(Xu, Hobbs et al., *Power & Energy Magazine*, 14(4), 2016)

Are they more robust against scenarios not considered?

Answer for WECC-wide analysis: Yes, the “Stochastic 5” 1st stage lines perform better against the withheld 15 scenarios than the “Base Case” (1 scenario) 1st stage lines

**Cost increase by scenario for “Base Case” vs. “Stochastic 5” plan
(equal probabilities, 300 bus model, “wait-&-see” decisions optimized by scenario)**



★ Included in “Stochastic 5” Model; other 15 scenarios not in model

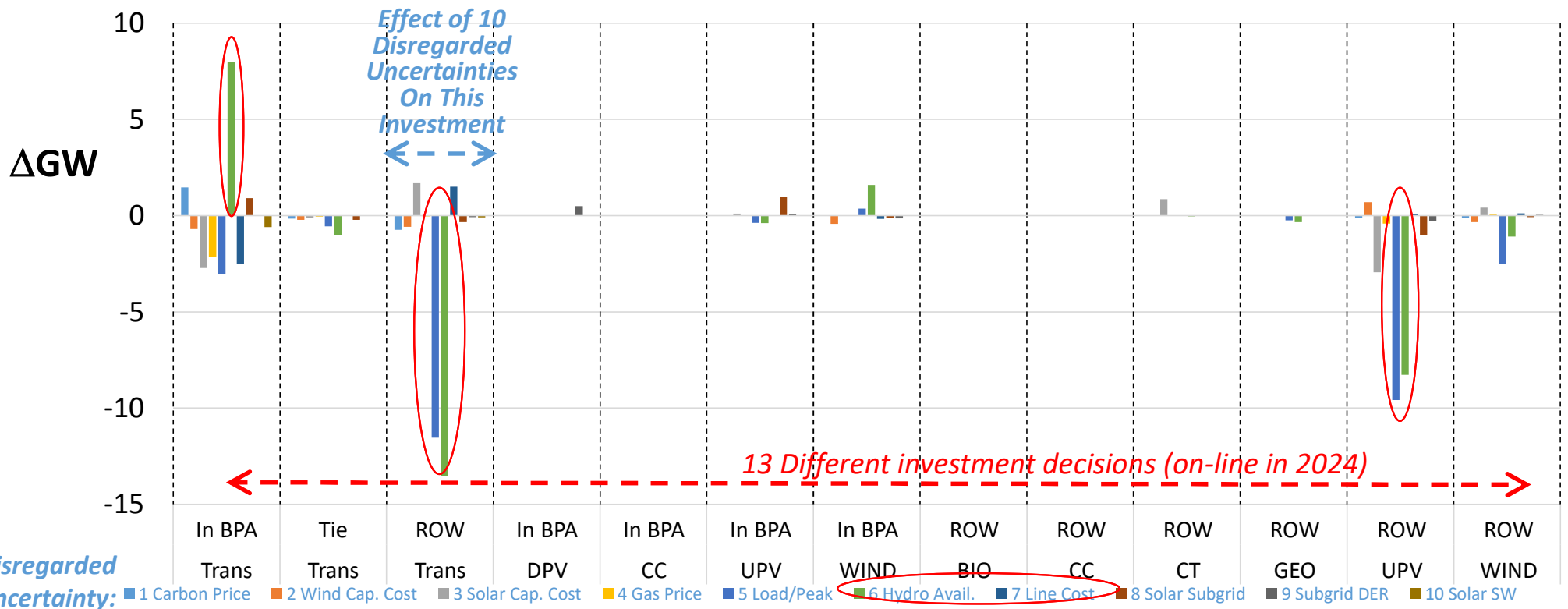
Q3: Which Uncertainties Matter Most?

- There are many uncertain variables: *which* might affect your plan?
 - ✓ Literature: a few scenarios yield most of the benefit of SP
 - ✓ Computationally efficient to focus on them

- Measuring effect: *If you consider uncertainty “A”, what happens to:*
 1. Near-term transmission investments? (build what and where?)
 2. Cost? (how much decrease because of more robust performance later?)

Q3: Change in 2018 Investments

- For each of 10 uncertainties: drop 1 at a time (use its “medium” value in all scenarios) and re-run SP
- Changes” in 1st stage investment compared to “all uncertainty” SP
 - “+” → dropping uncertainty *increases* investment
 - “-” → *decreased* investment

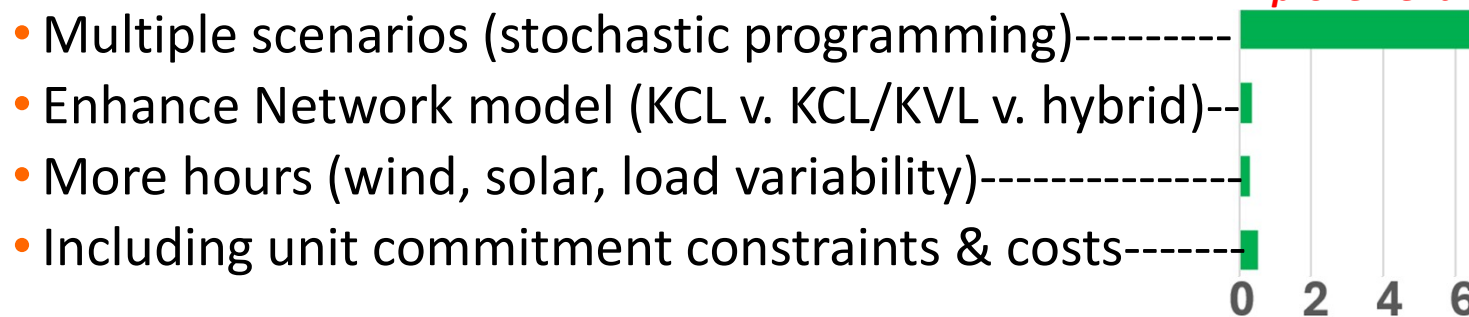


Q4: Benefits of SP vs. Other Model Enhancements

(Xu, Hobbs, *IET Generation, Transmission & Distribution*, 13(13), 2019)

What is the economic value of improving realism of transmission planning models?

Compare for WECC:



(Compared to \$26B net benefit for base plan)

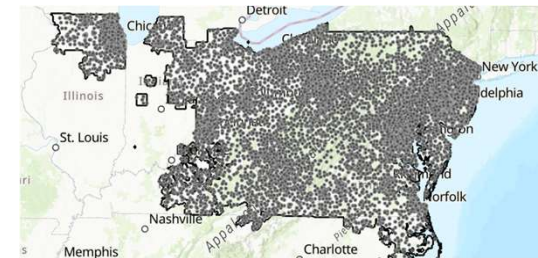
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V. AI Can Already Help with Operations & Planning

➤ AI copes with rapidly increasing dimensionality

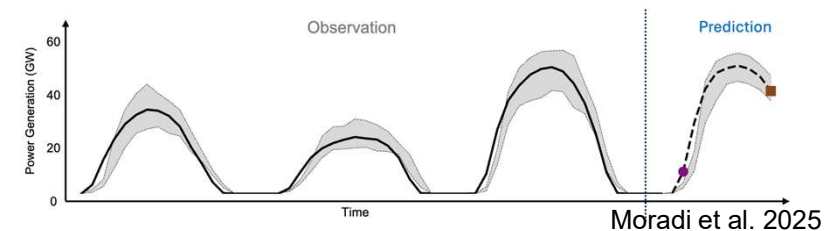
- More nodes (TSO-DSO integration) & time periods
- More physical accuracy (inverter-based resources; AC instead of pipes & bubbles)



PJM:
16997 nodes

➤ AI can create better uncertainty sets

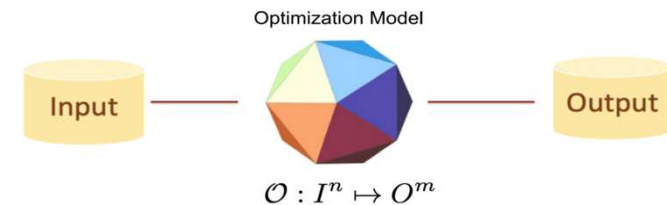
- “Polynomial Chaos Expansion” captures multiple uncertainty sources and accounts for correlations



Moradi et al. 2025

➤ AI enables tractable sensitivity analysis

- Solve problem many times quickly over different inputs



AI4OPT &
van Hentenryck

➤ AI enables mapping of the input uncertainty into output uncertainty:

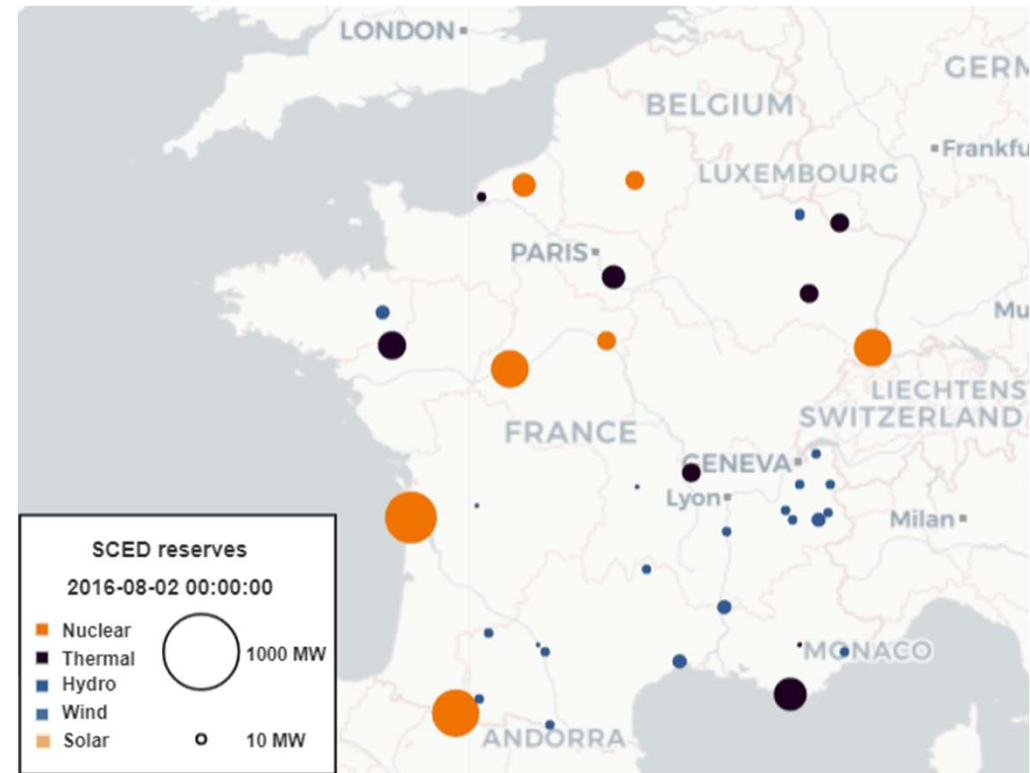
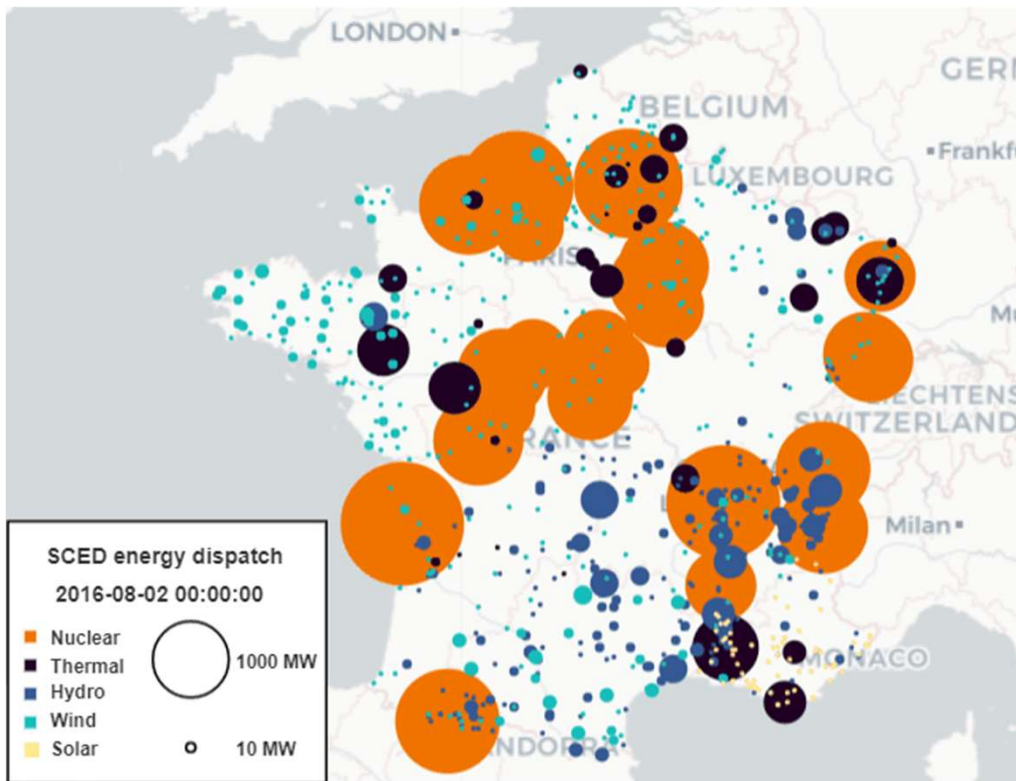
- Discrete distributions for binary decisions (e.g., build line)
- Continuous distributions for capacity decisions (e.g., build X of generation capacity of type Y)



Liang et al. 2023.

Example: Security-Constrained Economic Dispatch

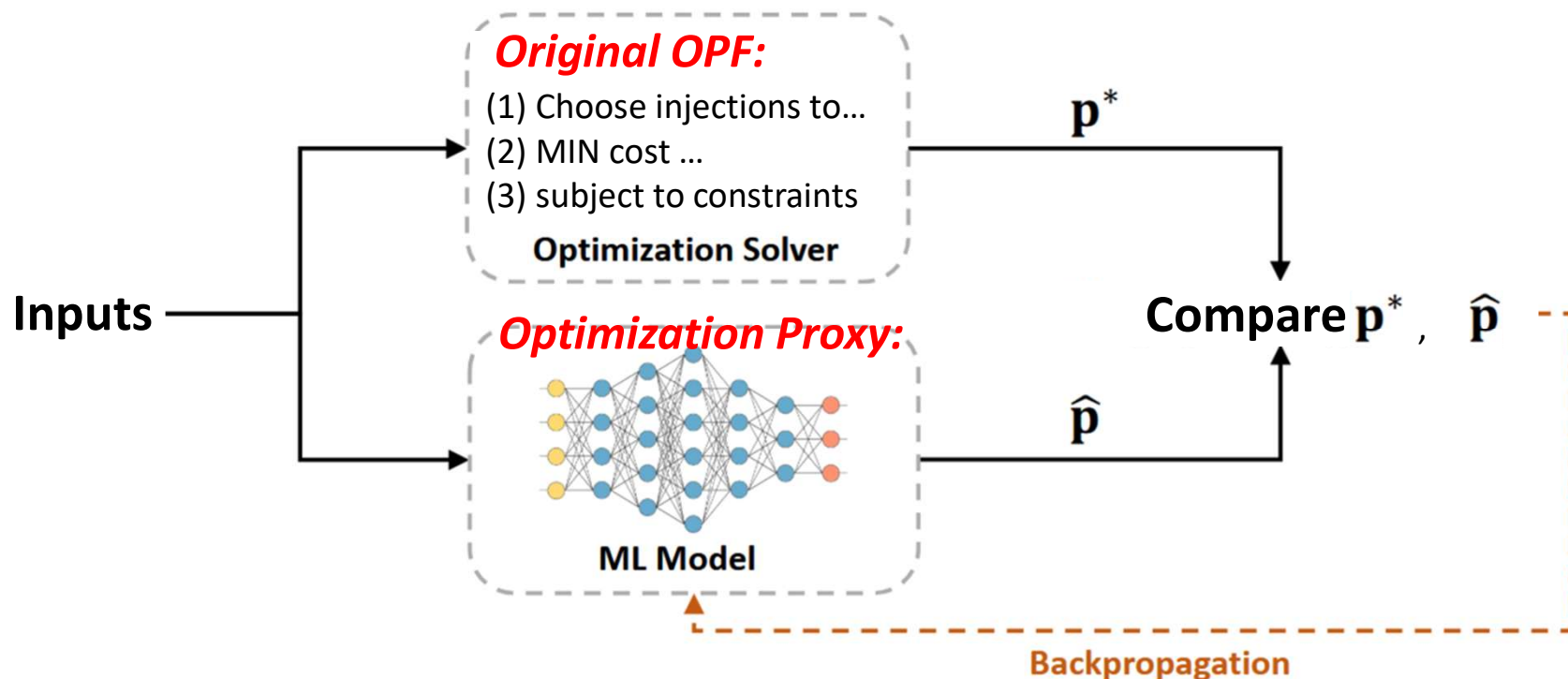
(courtesy of Pascal van Hentenryck)



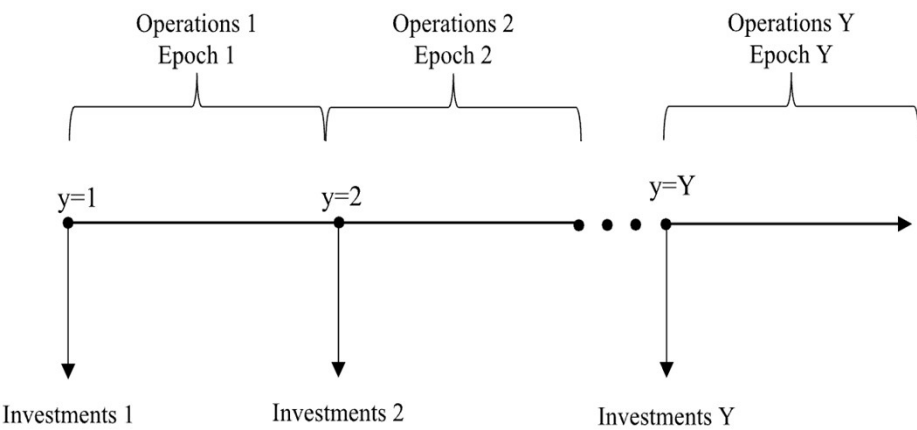
AI (Neural Net) AC-OPF Solution (Chen, Tanneau, Van Hentenryck 2023)

➤ Example (case 30000_goc):

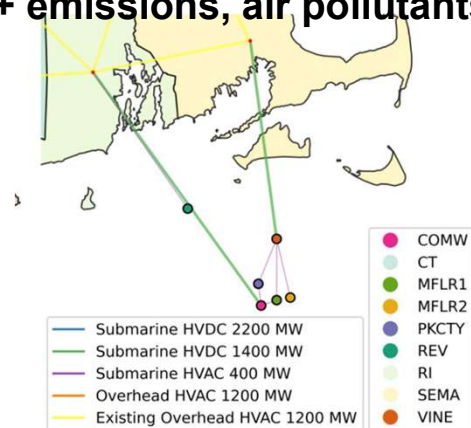
- ✓ 30,000 busses, 3526 generators, 10,648 lines
- ✓ End-to-End Learning and Repair (E2ELR): Input sampling time 63 hr; Training time 20 min (below)
- ✓ E2ELR AI solution: 11.1 ms (Cf. Gurobi: 4746 ms)



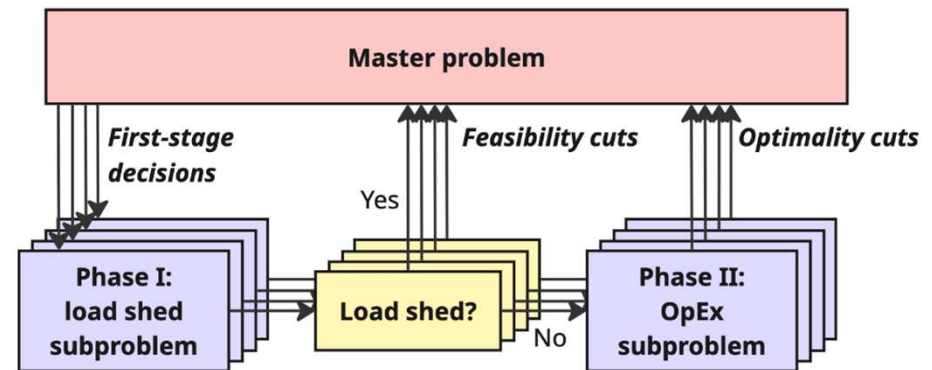
Opportunity for AI: Fast Operating Subproblem Solutions for Decomposition-based Multi-Stage Transmission and Generation Planning



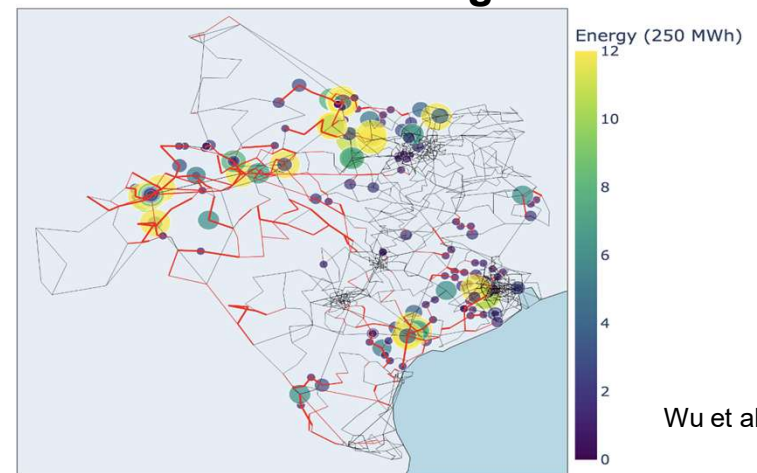
Multi-objective optimization
(cost + emissions, air pollutants + resiliency)



Khanal, 2024



2045 TEP + Storage



Wu et al, 2025

For additional decomposition example, see EPRI Sponsored Report by Qingyu Xu and BF Hobbs, JHSMINE Version 2.1

Conclusion

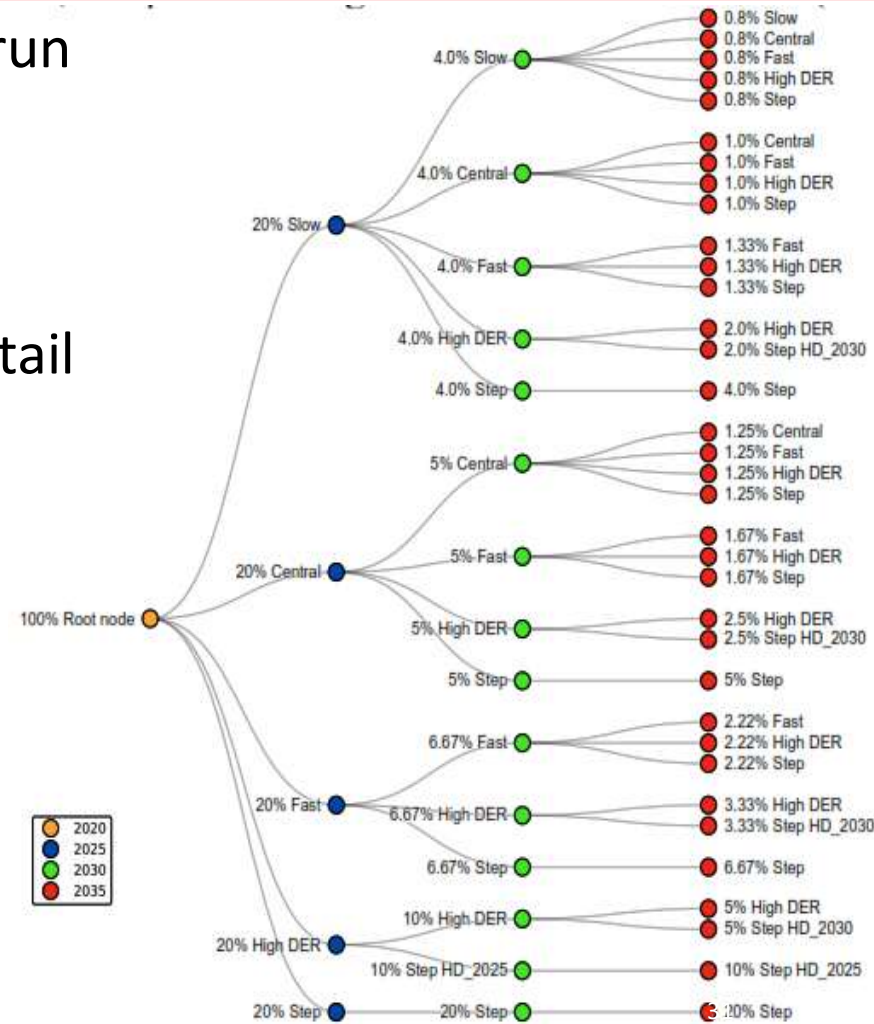
➤ Uncertainty-aware planning with many long-run scenarios is *practical* using SP or RDM

- E.g., AEMO Integrated System plan
(Figure source: Pierluigi Mancarella, UMelbourne, personal communication)

➤ Decomposition & AI will allow much more detail

➤ Considering uncertainty makes *by far* the most difference in first-stage transmission decisions and economic benefits

- All forecasts wrong, so consider a wide range of scenarios
- And how our system would adapt to them



Bibliography

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