

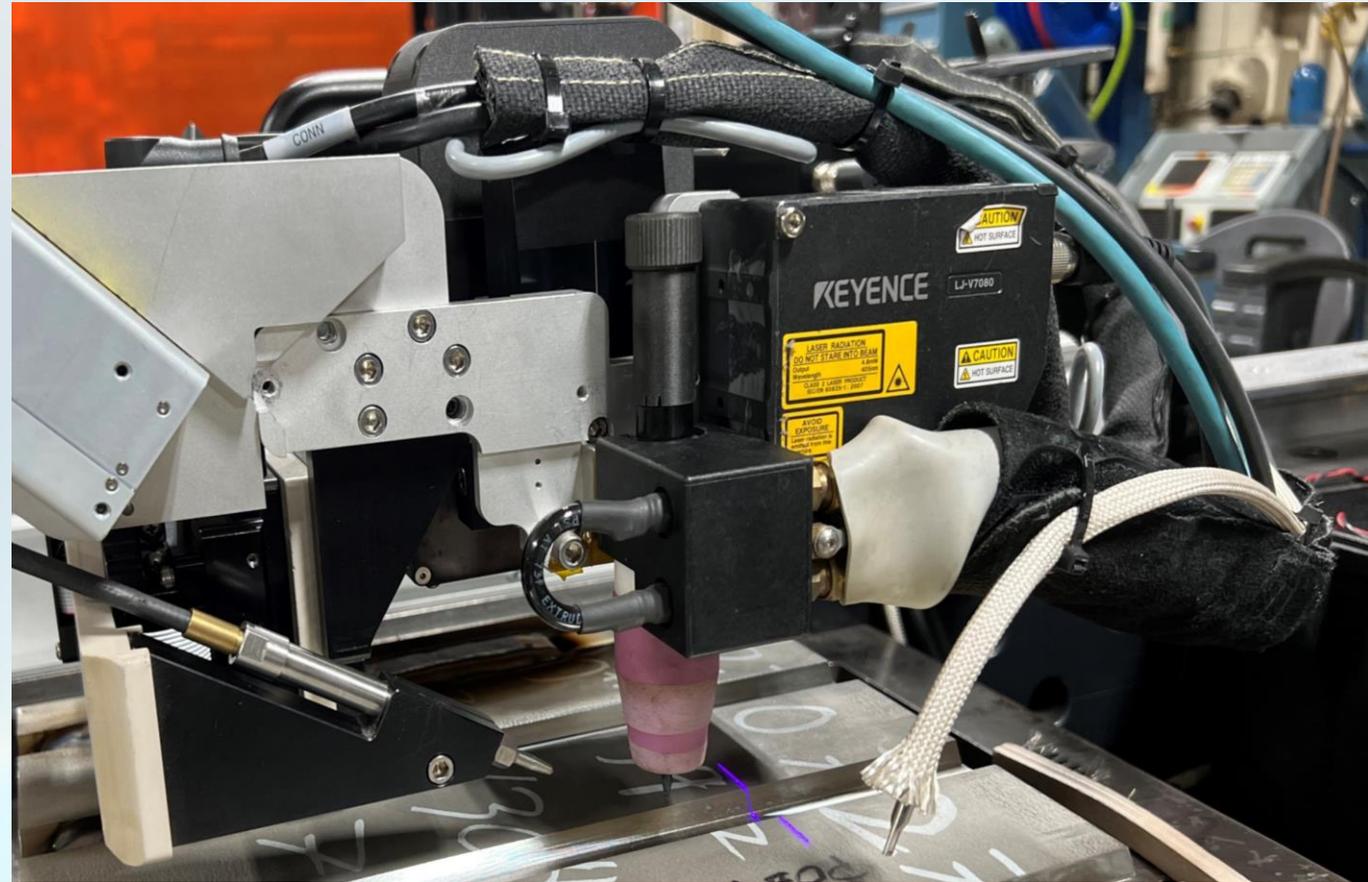
The Use of AI in Welding

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Principal Team Lead, Welding and Repair Technology Center

AKL 2026 – International Laser Technology Congress
Process Monitoring Session

Adaptive Feedback Welding: Problem Definition

- Operator-driven, “mechanized” arc welding is used for many safety-related welds in the nuclear industry
- Availability of skilled certified welding operators has become increasingly scarce since the turn of the century
- Weld quality/productivity will become a significant issue in the future as the industry struggles to maintain skilled welders



EPRI Adaptive Feedback Welding System

Problem Definition

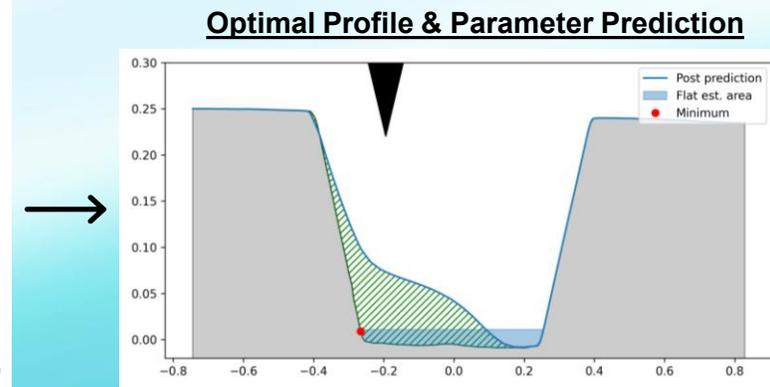
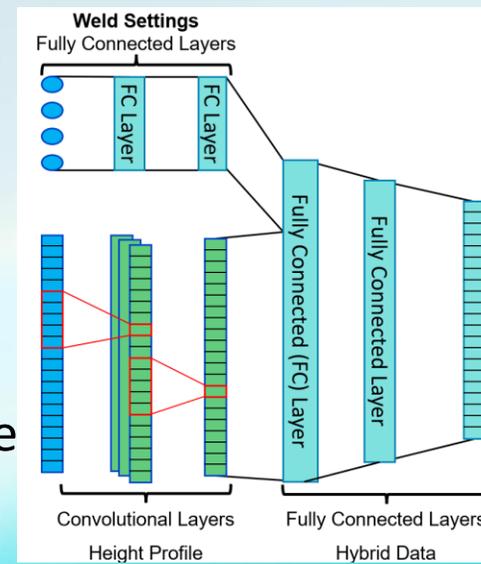
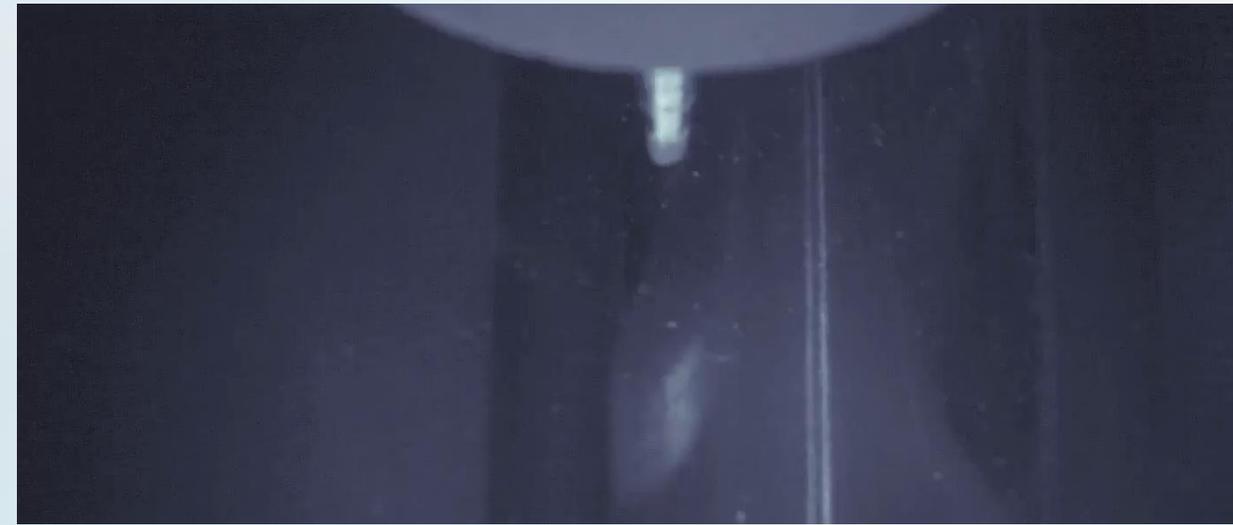
Solution: Artificially Intelligent Autonomous Welding

Real-time data to support adaptive control (“eyes and ears”)

- Real-time image data processing from vision system
- Real-time weld, groove, and joint profile data from laser profiler
- Weld parameter data acquisition
- Acoustics (microphone) data

Solution to address reduced welding workforce (“brain”)

- The next evolution for the welding process is to drive it towards autonomous operation, accomplished through real-time data processing / feedback and incorporation of artificial intelligence algorithms



Key Project Research Needs

Collaborative Model for Commercial Implementation



Welding Equipment Sensor
Data Collection Test
Algorithms



Data Processing
Algorithm & Neural Network
Development

AI
MODEL



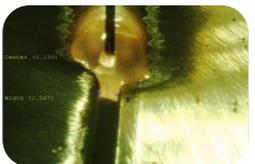
Commercial
Implementation
Adaptive Weld
System for Industry
Integration



Different Equipment
Liburdi Equipment



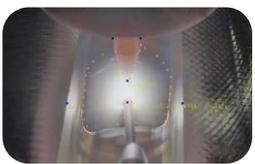
Multiple Processes
GMAW, GTAW



Weaving
Oscillating Electrode



Multiple Applications
Orbital Welding



Convolutional Neural Network

Semantic Segmentation:

Real-time Image Processing (3X speed)

Wire Position Control

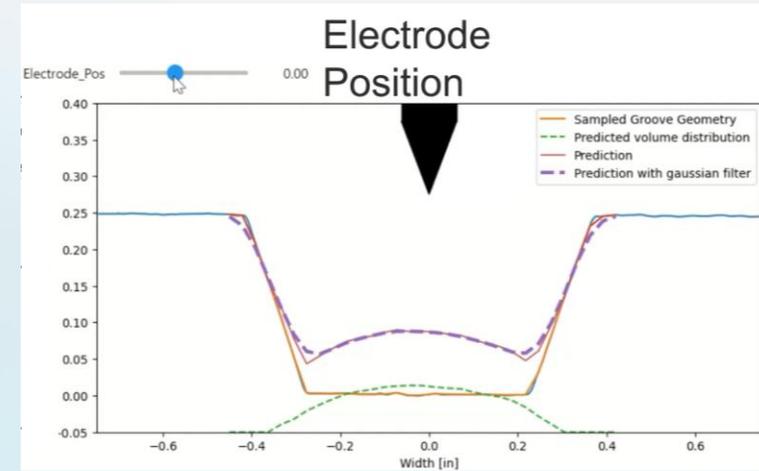
Weld Pool Shape Monitoring

Different
Cameras

Optimal Parameter Selection Tool

Operator Defines:

- WFS & TS
- Current & Voltage
- Cap (height, width)
- Parameter Limits



For all parameter combinations

Calculate Score

Predict weld bead shape

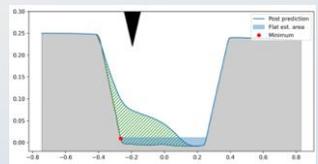
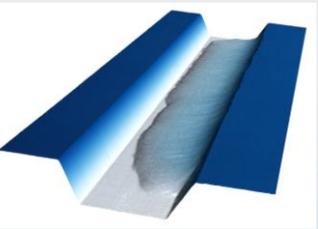
Compare Score with best weld found so far

Get new parameter combination

Return & Upload Best Combination

Begin Welding & Repeat

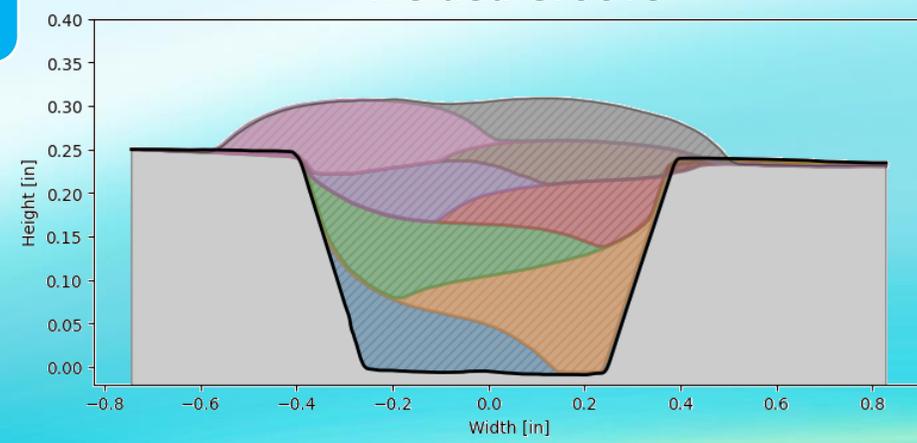
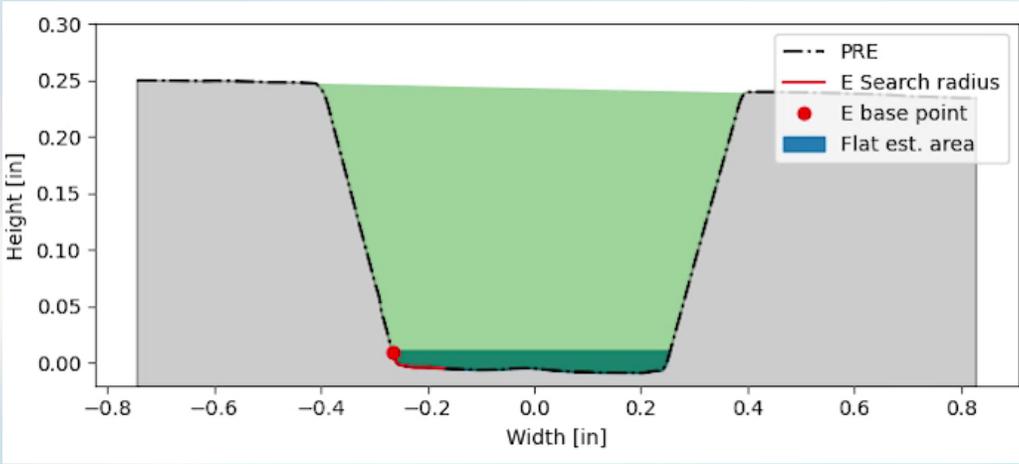
Actual Profile of Autonomously Welded Groove



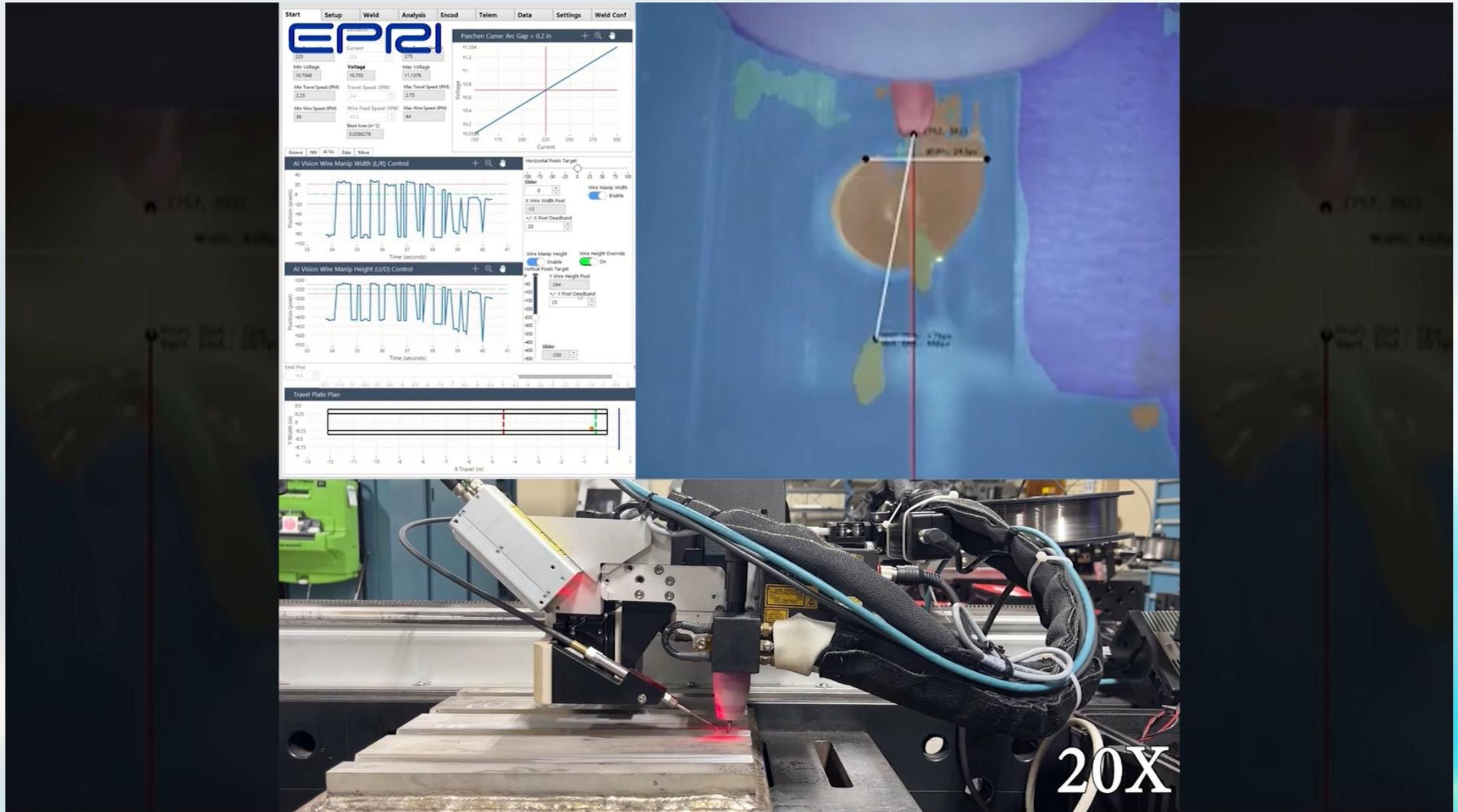
Load Profile Data

Calculate Cross-Section

Define Parameter Combinations

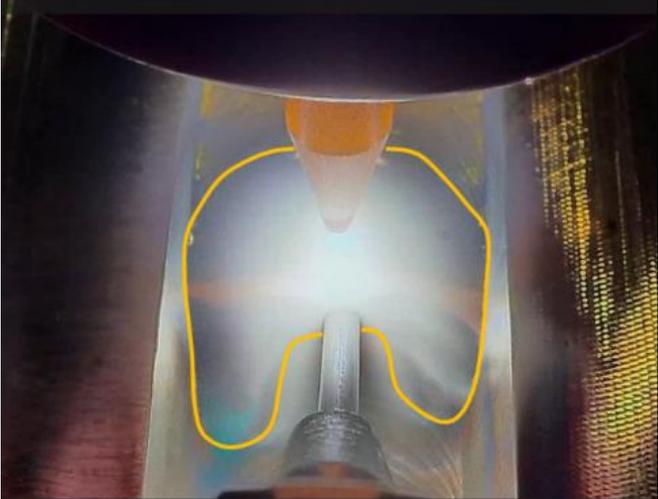


Adaptive Welding Demo – EPRI System



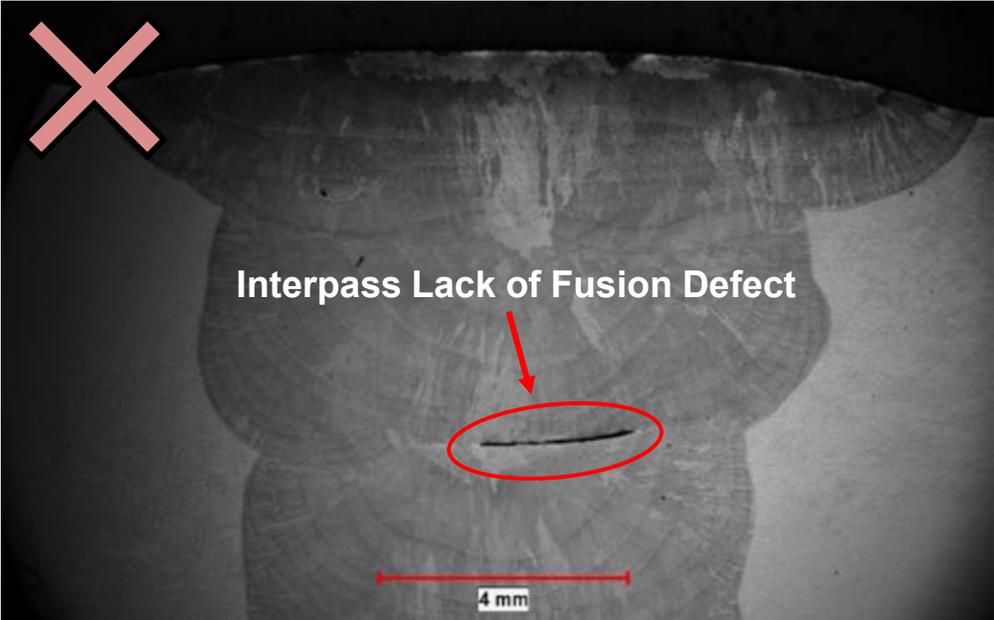
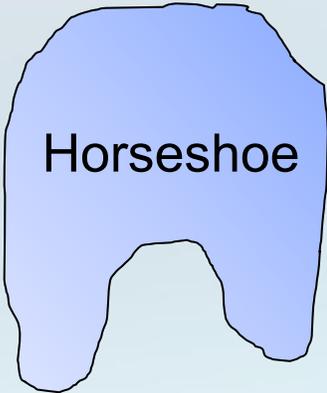
Real Time Detection of Weld Defects

- Weld Pool Shape -> Presence of Defects



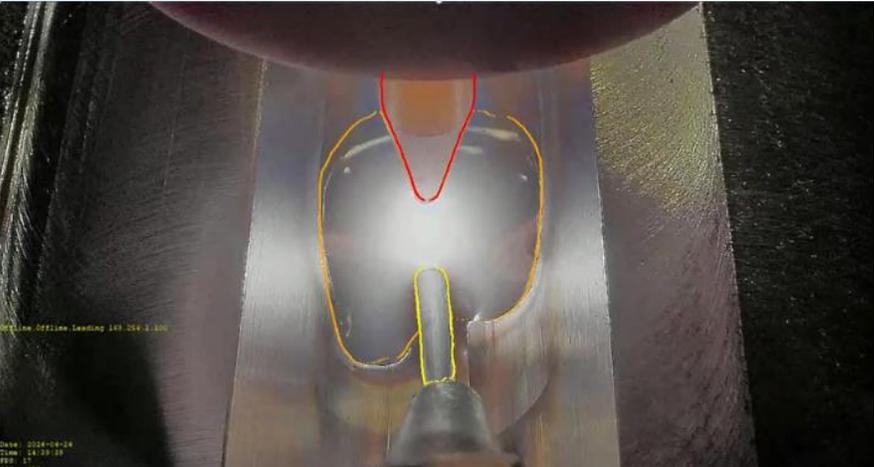
Do Nothing →

- Traveling Too Fast
- Excessive Wire Feed Speed

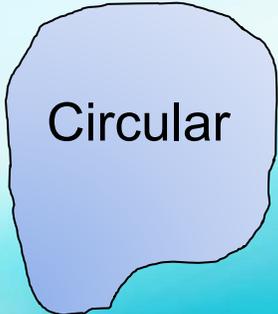


↓ **Adaptive Correction**

- Decrease Travel Speed
- Decrease Wire Feed Speed

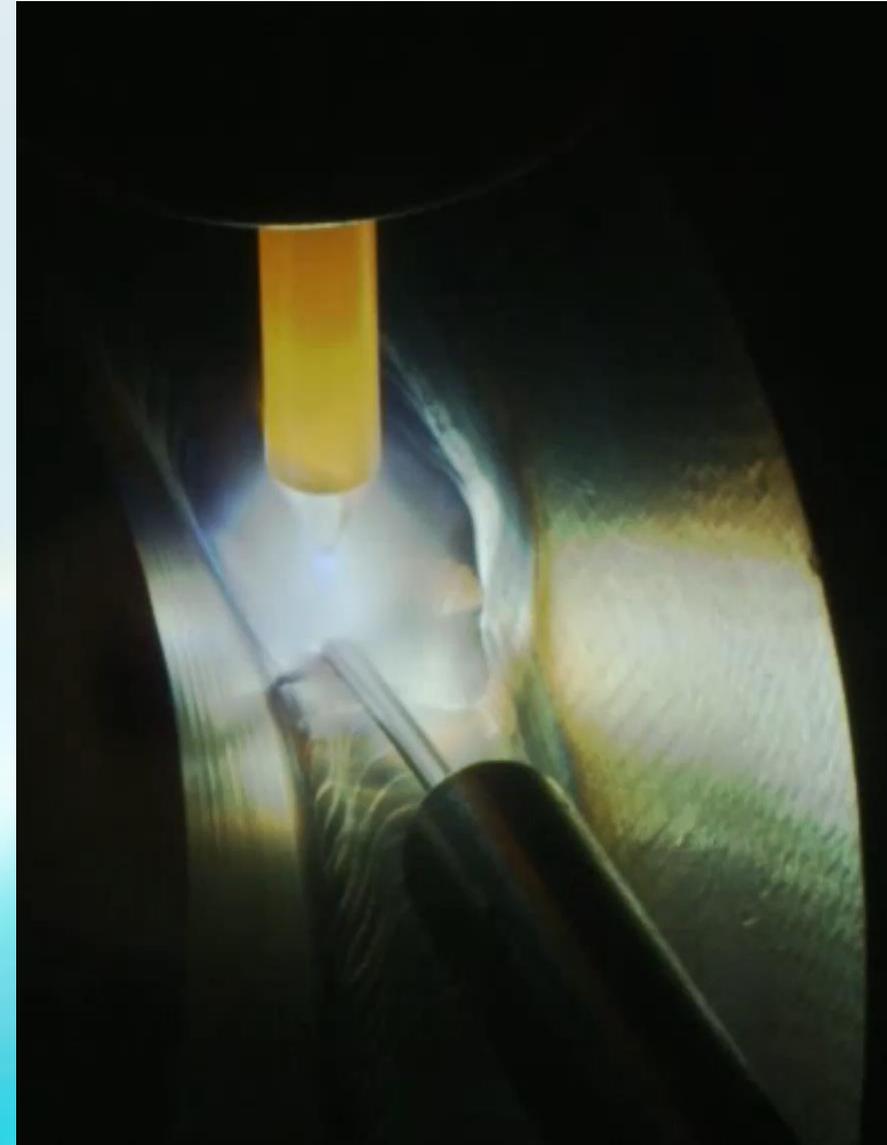


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Technology Transfer: Canister Closure Welding at Hanford Site

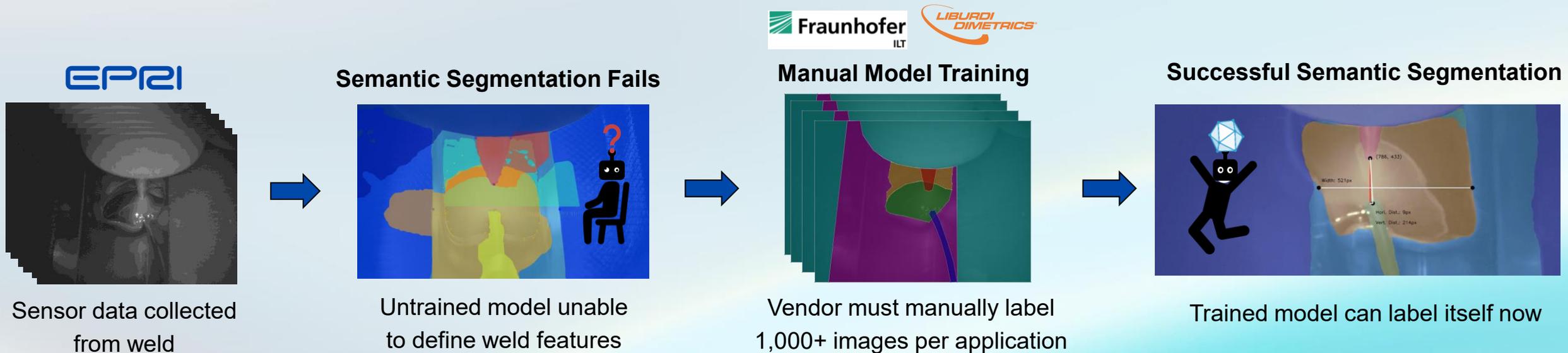
- Adaptive feedback welding system to be deployed in 2025 to autonomously perform high radiation cesium-strontium canister closure welds at the U.S. Department of Energy Hanford Site
 - Collaboration with U.S. DOE, Fluor, Liburdi Dimetrics, and Central Plateau Cleanup Company



Next Steps to Improve AI Algorithms: Semi-Supervised Learning

▪ Supervised Learning:

- Developed AI algorithms currently require manual labeling of 1000+ images per application to train model
- Tedious manual labeling presents bottleneck for commercial implementation



▪ Phase 2: Development of Semi-supervised Learning Approach

- Develop improved labeling methods to potentially reduce required number of manually labeled images to between 10 and 50 per application

Next Steps to Improve AI Algorithms: Penetration Monitoring

Collaboration with Oak Ridge National Laboratory

Partial penetration



Full penetration

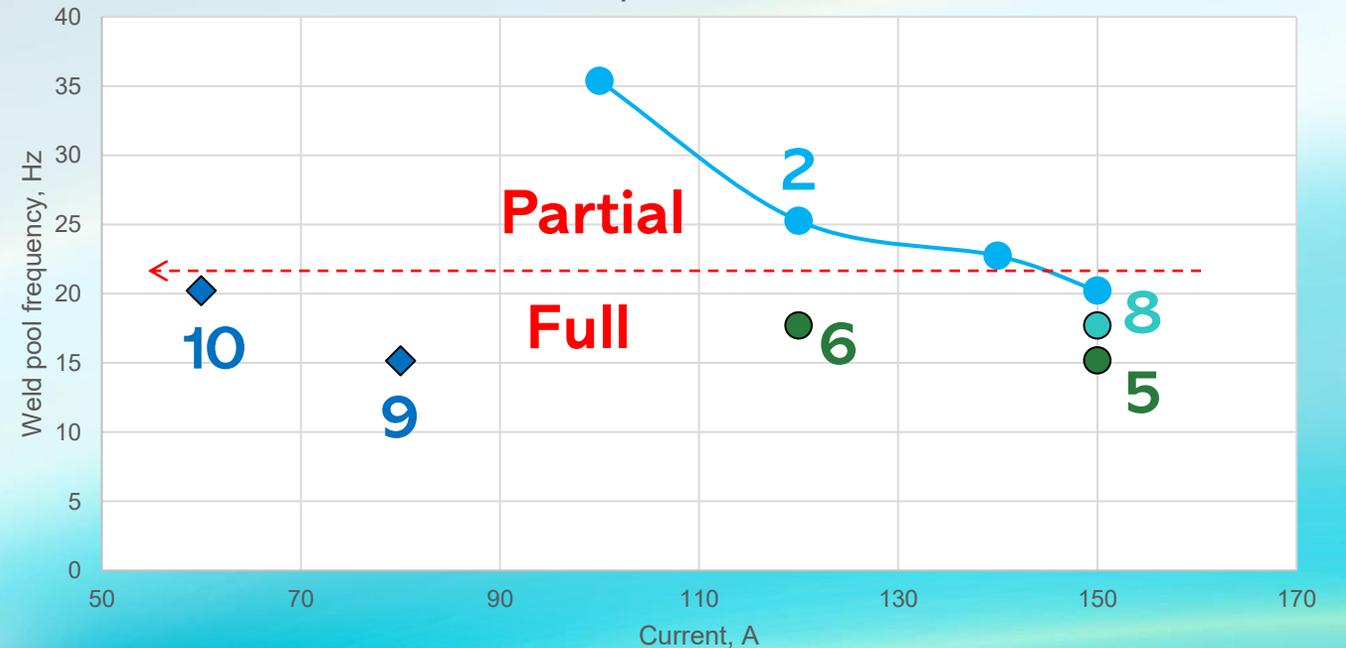


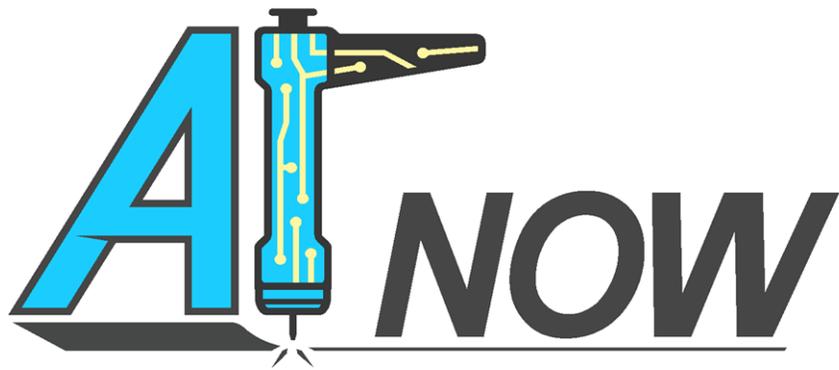
Testing	Thickness, mm	Speed, mm/s	BKG Current, A	PK Current, A	Pulse Duration, %	Comment
1	2.5	4.3	100	200	5	Partial
2	2.5	4.3	120	240	5	Partial
3	2.5	4.3	140	280	5	Partial
4	2.5	4.3	150	300	5	Full
5	2.5	3.7	150	300	5	Full
6	2.5	3.7	120	240	5	Full
8-wire	2.5	3.7	150	300	5	Full-wire
9	1.5	4.3	80	160	5	Full
10	1.5	4.3	60	120	5	Full

Weld pool dynamics (x34 slow motion)



Weld pool vibration





Artificially Intelligent, Next-Gen Optimized Welding Implementation Program

New EPRI Supplemental Program to
accelerate industry implementation of
intelligent AI-driven welding

Goals

- Accelerate transfer and deployment of EPRI adaptive welding technology
- Develop modular, platform-agnostic control system supporting diverse sensors & welding equipment configurations
- Create R&D consortium to enable cross-sector collaboration



Benefits

- Opportunity for application-specific algorithm training, demonstrations, & tailored implementation support (Tier 1)
- License rights to EPRI-developed, field-validated adaptive control algorithms & version updates (Tier 2)
- Significant cost savings (reduced oversight, repairs, inspections)



EPRI Roles

- Provide members early influence over acceptance standards, training, system architecture & priorities to meet member needs.
- Promote an industry-supported approach to qualification, validation, & field demonstrations, reducing time, cost, & risk of transitioning autonomous welding from concept to deployment



Connecting Members

- Initial outreach underway. Webinars and scoping calls to be held with interested organizations
- Tiered membership model based on desired level of engagement
- Anticipated launch: Q4 2026 with initial demonstrations & prototyping in Q2 2027



Applications Currently Being Explored for Adaptive Welding

- Nuclear:

- Primary loop construction (narrow groove welding)
- Spent nuclear fuel canister fabrication
- Fabrication of advanced reactor piping system & pressure-retaining structures
- Main Steam Line Replacements
- Additive manufacturing (GMAW, laser DED)
- Structural module fabrication
- Others?

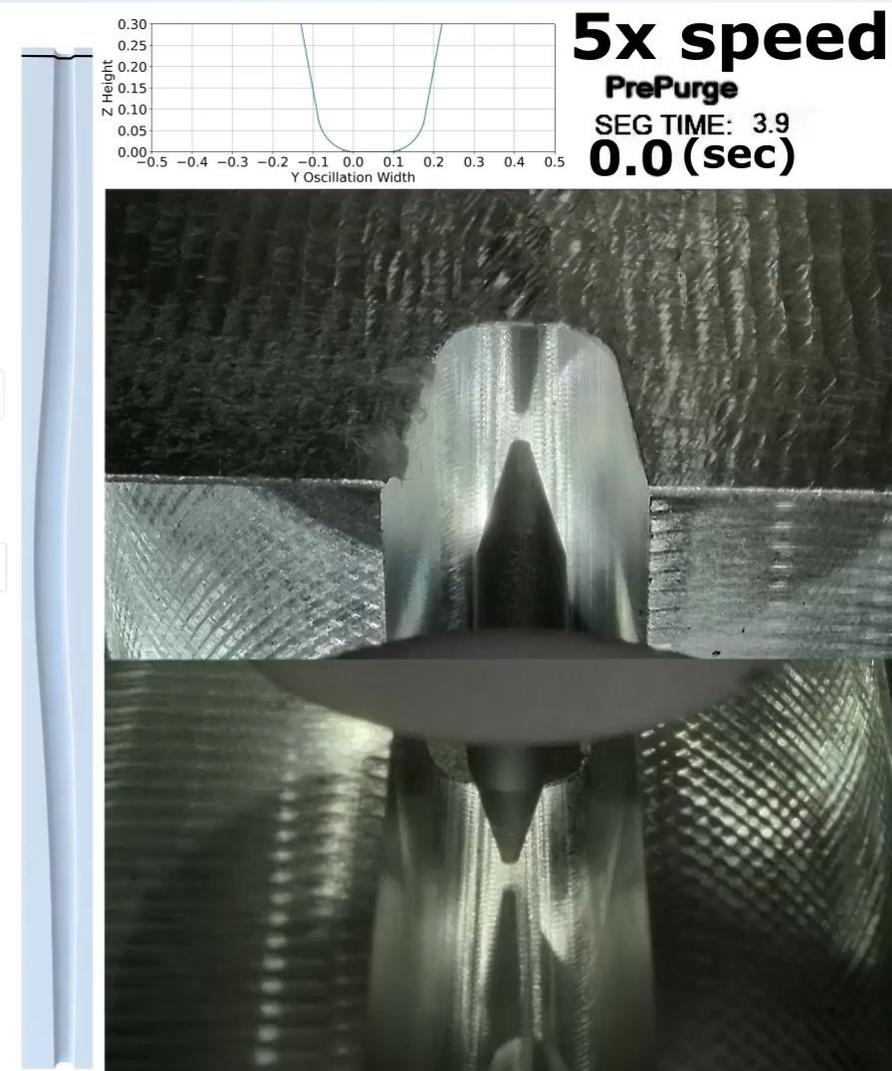
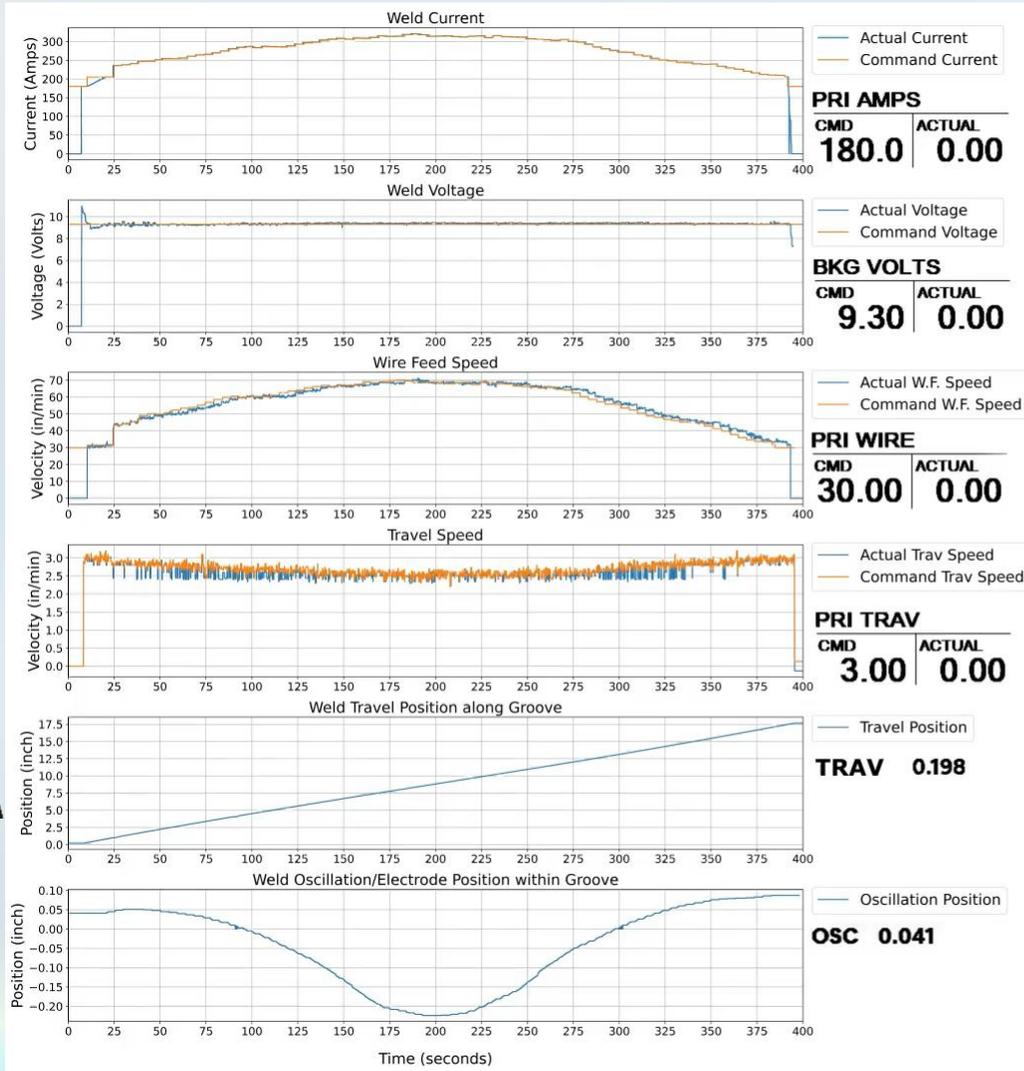
- Non-Nuclear:

- Thin-wall orbital piping (Blue Origin – Rocket Engines)
- Piping and hull joining (Shipbuilding)
- Off-shore wind turbine fabrication

A person's hands are shown holding a globe of the Earth. A glowing welding torch is superimposed over the globe, with a bright light emanating from its tip. The background is a teal gradient with faint, glowing lines and particles, suggesting a futuristic or technological theme.

ADAPTIVE WELDING DEMO EXAMPLES (LIBURDI)

Adaptive Welding – Variable Groove Width Demonstration Coupon



This product was developed and  using research

Adaptive Welding – 2” Schedule 40 Pipe, 37.5 Bevel, Open Root Stainless Steel



● NETWORK ● IN SEQUENCE ● ARC ON
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SEG ADV STOP WELD MODE Segment 1 PURGE ON WIRE ON TRAVEL FWD

PRI AMPS CMD: 85.00 ACTUAL: 0.00		PRI VOLTS CMD: 8.30 ACTUAL: 0.00		PRI WIRE CMD: 33.37 ACTUAL: 0.00		PRI TRAV CMD: 1.50 ACTUAL: 0.00		OSC WIDTH 0.075
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AVC - OSC SEG TIME: 16.6 WIRE POSITION

IN ▲ OUT
▼

TRAVEL
REV FWD

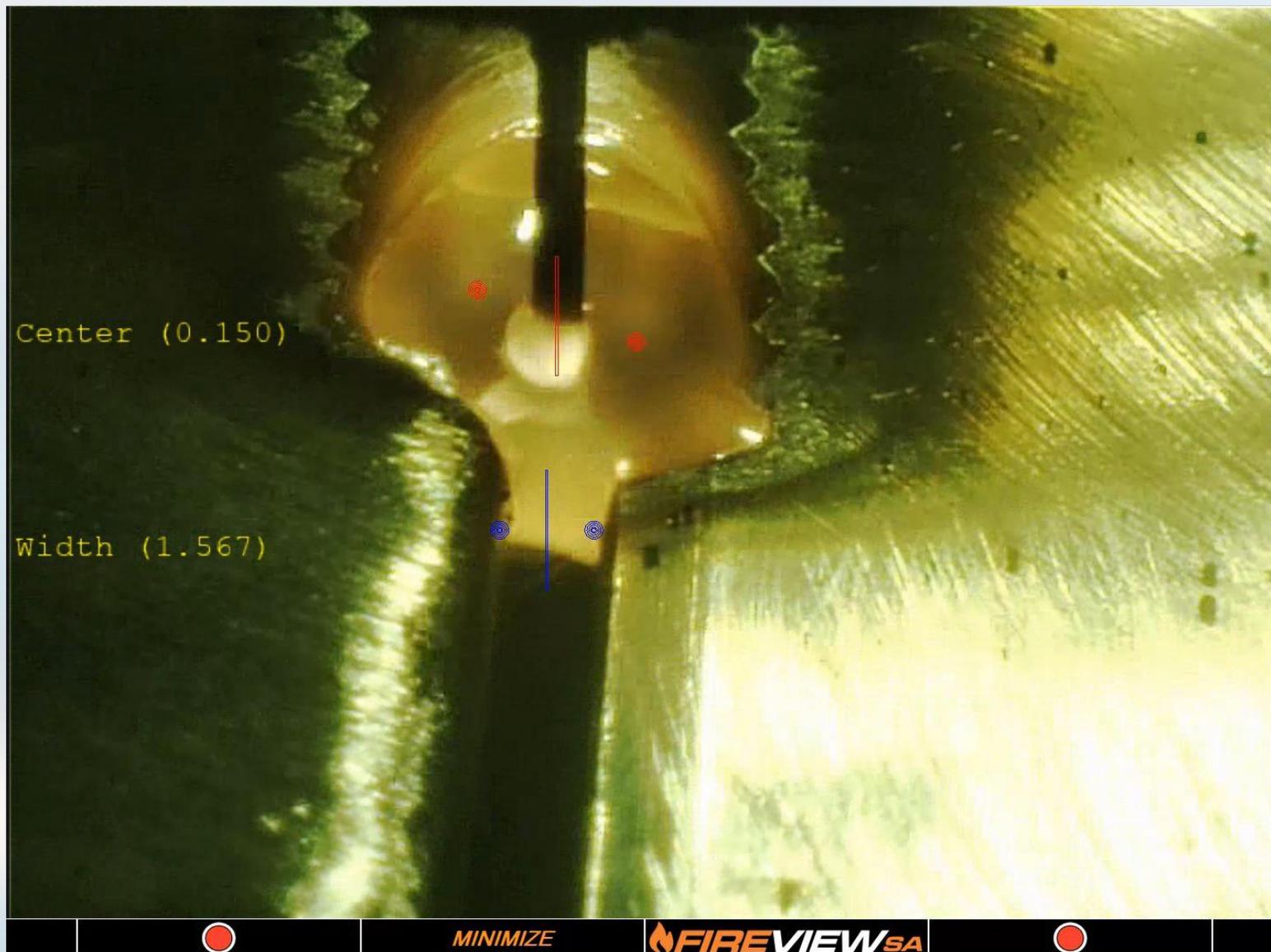
WIRE
IN OUT

IN ▲ OUT
▼

Settings Tools Designer Program FirePilot PATH SETUP Load Schedule Data Log Logs



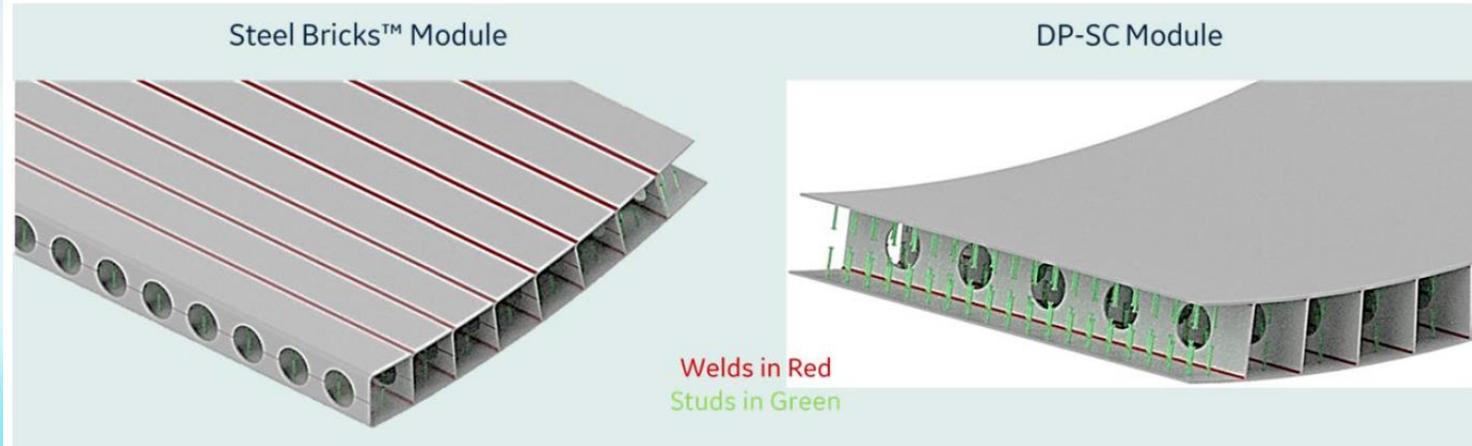
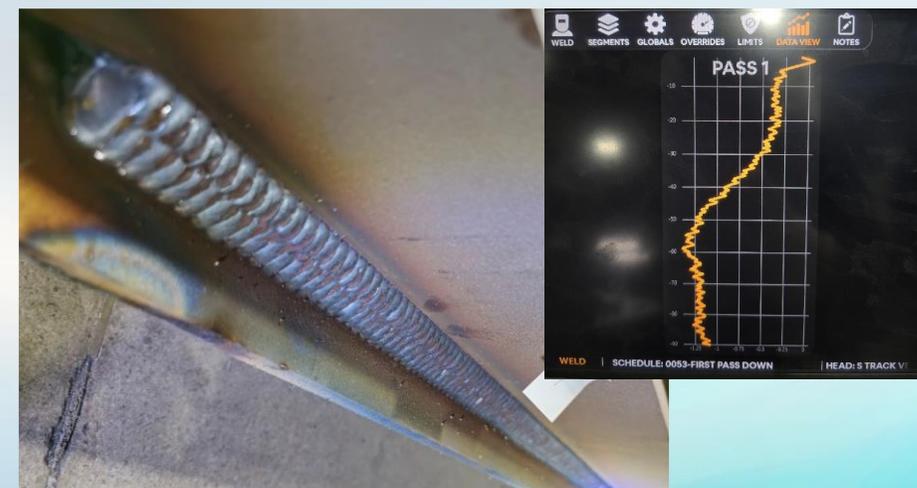
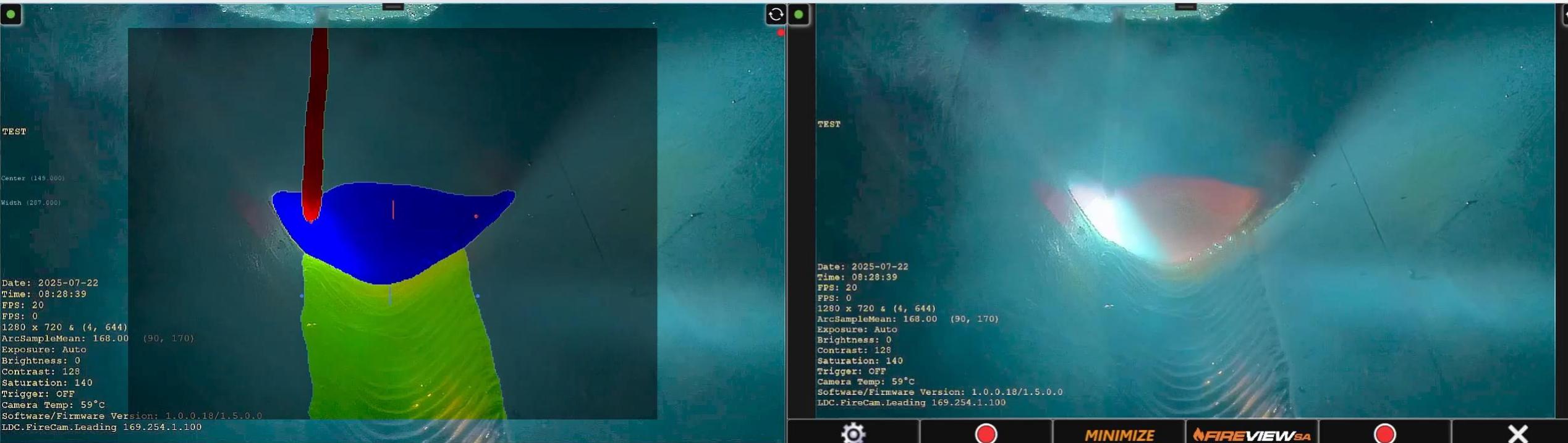
Adaptive Welding – 6” Schedule 10 Pipe, No Backing Gas Stainless Steel



1. Joint Tracking
2. Root Opening Measurement
3. Adaptive Response:
 - Steering
 - Oscillation Width
 - Travel Speed
4. Process limit monitoring (i.e. mismatch)
5. Weld Pool Monitoring

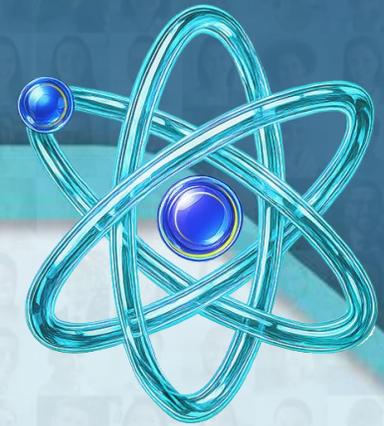


Adaptive Welding – GMAW Fillet Welding



Source: National Reactor Innovation Center, Advanced Construction Technology Initiative Program

EPRI



TOGETHER...SHAPING THE FUTURE OF ENERGY®